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Modeling Guidelines for High-Integrity Systems



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Modeling Guidelines for High-Integrity Systems

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Introduction

- “Motivation” on page 1-2
- “Guideline Template” on page 1-3
- “Model Advisor Checks for High-Integrity Modeling Guidelines” on page 1-4

Motivation

MathWorks intends the guidelines for engineers developing models and generating code for high-integrity systems using Model-Based Design with MathWorks products. The guidelines provide recommendations for creating Simulink models that are complete, unambiguous, statically deterministic, robust, and verifiable. The guidelines focus on model settings, block usage, and block parameters that impact simulation behavior or code generated by the Embedded Coder® product.

These guidelines do not assume that you use a particular safety or certification standard. The guidelines reference some safety standards where applicable, including:

- DO-178C / DO-331
- IEC 61508
- IEC 62304
- ISO 26262
- EN 50128
- MISRA C

The guidelines might also be applicable to related standards, including IEC 62304, and DO-254.

You can use the Model Advisor to support adhering to these guidelines. Each guideline lists the checks that are applicable to that guideline, or to parts of that guideline.

The guidelines do not address model style or development processes. For more information about creating models in a way that improves consistency, clarity, and readability, see the “MAB Modeling Guidelines” guidelines. Development process guidance and additional information for specific standards is available with the IEC Certification Kit (for ISO 26262 and IEC 61508) and DO Qualification Kit (for DO-178) products.

Disclaimer While adhering to the recommendations in the guidelines will reduce the risk that an error is introduced during development and not be detected, it is not a guarantee that the system being developed will be safe. Conversely, if some of the recommendations in the guidelines are not followed, it does not mean that the system being developed will be unsafe.

Guideline Template

Guideline descriptions are documented, using the following template. Companies that want to create additional guidelines are encouraged to use the same template.

ID: Title	<i>XX_nnnn</i> : Title of the guideline (unique, short)
Description	Description of the guideline
Prerequisites	Links to guidelines that are prerequisites to this guideline (ID: Title)
Notes	Notes for using the guideline
Rationale	Rationale for providing the guideline
Model Advisor Check	Title of and link to the corresponding Model Advisor check, if a check exists
References	References to standards that apply to guideline
See Also	Links to additional information
Last Changed	Version number of last change
Examples	Guideline examples

Model Advisor Checks for High-Integrity Modeling Guidelines

The Simulink Check Model Advisor provides High-Integrity System Modelling checks that you can use to verify compliance with safety standards, including:

- DO-178C / DO-331
- IEC 61508
- IEC 62304
- ISO 26262
- EN 50128

The high-integrity guidelines and their corresponding checks are summarized in the table. For the guidelines that do not have Model Advisor checks, it is not possible to automate checking of the guideline. Guidelines without a corresponding check are noted as not applicable.

To check compliance with High Integrity System Model standards, run the high-integrity checks from these Model Advisor folders:

- **By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems**
- **By Task > Modeling Standards for IEC 61508 > High-Integrity Systems**
- **By Task > Modeling Standards for IEC 62304 > High-Integrity Systems**
- **By Task > Modeling Standards for EN 50128 > High-Integrity Systems**
- **By Task > Modeling Standards for ISO 26262 > High-Integrity Systems**

For information on using the Model Advisor, see “Run Model Advisor Checks”.

High-Integrity Modeling Guideline	Model Advisor Checks
“hisl_0001: Usage of Abs block” on page 2-2	“Check usage of Abs blocks” (Simulink Check)
“hisl_0002: Usage of Math Function blocks (rem and reciprocal)” on page 2-3	“Check usage of Math Function blocks (rem and reciprocal functions)” (Simulink Check)
“hisl_0003: Usage of Square Root blocks” on page 2-5	Not applicable
“hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)” on page 2-7	“Check usage of Math Function blocks (log and log10 functions)” (Simulink Check)
“hisl_0005: Usage of Product blocks” on page 2-10	Not applicable
“hisl_0006: Usage of While Iterator blocks” on page 2-16	“Check usage of While Iterator blocks” (Simulink Check)
“hisl_0007: Usage of For Iterator or While Iterator subsystems” on page 2-17	“Check usage of For and While Iterator subsystems” (Simulink Check)
“hisl_0008: Usage of For Iterator Blocks” on page 2-18	“Check usage of For Iterator blocks” (Simulink Check)

High-Integrity Modeling Guideline	Model Advisor Checks
"hisl_0010: Usage of If blocks and If Action Subsystem blocks" on page 2-19	"Check usage of If blocks and If Action Subsystem blocks" (Simulink Check)
"hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks" on page 2-21	"Check usage of Switch Case blocks and Switch Case Action Subsystem blocks" (Simulink Check)
"hisl_0012: Usage of conditionally executed subsystems" on page 2-23	"Check usage of conditionally executed subsystems" (Simulink Check)
"hisl_0013: Usage of data store blocks" on page 2-28	"Check safety-related diagnostic settings for data store memory" (Simulink Check)
"hisl_0015: Usage of Merge blocks" on page 2-30	"Check usage of Merge blocks" (Simulink Check)
"hisl_0016: Usage of blocks that compute relational operators" on page 2-38	"Check for Relational Operator blocks that equate floating-point types" (Simulink Check)
"hisl_0017: Usage of blocks that compute relational operators (2)" on page 2-39	"Check usage of Relational Operator blocks" (Simulink Check)
"hisl_0018: Usage of Logical Operator block" on page 2-40	"Check usage of Logical Operator blocks" (Simulink Check)
"hisl_0019: Usage of bitwise operations" on page 2-41	"Check usage of bit operation blocks" (Simulink Check)
"hisl_0020: Blocks not recommended for MISRA C:2012 compliance" on page 7-12	"Check for blocks not recommended for C/C++ production code deployment" (Simulink Check) "Check for blocks not recommended for MISRA C:2012" (Simulink Check)
"hisl_0021: Consistent vector indexing method" on page 2-32	"Check for inconsistent vector indexing methods" (Simulink Check)
"hisl_0022: Data type selection for index signals" on page 2-34	"Check data types for blocks with index signals" (Simulink Check)
"hisl_0023: Verification of model and subsystem variants" on page 2-35	"Check for variant blocks with 'Generate preprocessor conditionals' active" (Simulink Check)
"hisl_0024: Inport interface definition" on page 2-24	"Check for root Inports with missing properties" (Simulink Check)
"hisl_0025: Design min/max specification of input interfaces" on page 2-25	"Check for root Inports with missing range definitions" (Simulink Check)
"hisl_0026: Design min/max specification of output interfaces" on page 2-26	"Check for root Outports with missing range definitions" (Simulink Check)
"hisl_0028: Usage of Reciprocal Square Root blocks" on page 2-6	Not applicable

High-Integrity Modeling Guideline	Model Advisor Checks
"hisl_0029: Usage of Assignment blocks" on page 2-11	"Check usage of Assignment blocks" (Simulink Check)
"hisl_0031: Model file names" on page 6-2	"Check model file name" (Simulink Check)
"hisl_0032: Model object names" on page 6-3	"Check model object names" (Simulink Check)
"hisl_0033: Usage of Lookup Table blocks" on page 2-43	"Check usage of lookup table blocks" (Simulink Check)
"hisl_0034: Usage of Signal Routing blocks" on page 2-36	"Check usage of Signal Routing blocks" (Simulink Check)
"hisl_0036: Configuration Parameters > Diagnostics > Saving" on page 5-7	"Check safety-related diagnostic settings for saving" (Simulink Check)
"hisl_0037: Configuration Parameters > Model Referencing" on page 5-24	"Check safety-related model referencing settings" (Simulink Check)
"hisl_0038: Configuration Parameters > Code Generation > Comments" on page 5-32	"Check safety-related code generation settings for comments" (Simulink Check)
"hisl_0039: Configuration Parameters > Code Generation > Interface" on page 5-33	"Check safety-related code generation interface settings" (Simulink Check)
"hisl_0040: Configuration Parameters > Solver > Simulation time" on page 5-2	"Check safety-related solver settings for simulation time" (Simulink Check)
"hisl_0041: Configuration Parameters > Solver > Solver options" on page 5-3	"Check safety-related solver settings for solver options" (Simulink Check)
"hisl_0042: Configuration Parameters > Solver > Tasking and sample time options" on page 5-4	"Check safety-related solver settings for tasking and sample-time" (Simulink Check)
"hisl_0043: Configuration Parameters > Diagnostics > Solver" on page 5-8	"Check safety-related diagnostic settings for solvers" (Simulink Check)
"hisl_0044: Configuration Parameters > Diagnostics > Sample Time" on page 5-9	"Check safety-related diagnostic settings for sample time" (Simulink Check)
"hisl_0045: Configuration Parameters > Math and Data Types > Implement logic signals as Boolean data (vs. double)" on page 5-5	"Check safety-related optimization settings for logic signals" (Simulink Check)
"hisl_0046: Configuration Parameters > Simulation Target > Block reduction" on page 5-25	"Check safety-related block reduction optimization settings" (Simulink Check)

High-Integrity Modeling Guideline	Model Advisor Checks
"hisl_0047: Configuration Parameters > Code Generation > Code Style" on page 5-34	"Check safety-related code generation settings for code style" (Simulink Check)
"hisl_0048: Configuration Parameters > Math and Data Types > Application lifespan (days)" on page 5-6	"Check safety-related optimization settings for application lifespan" (Simulink Check)
"hisl_0049: Configuration Parameters > Code Generation > Identifiers" on page 5-35	"Check safety-related code generation identifier settings" (Simulink Check)
"hisl_0051: Configuration Parameters > Code Generation > Optimization > Loop unrolling threshold" on page 5-26	"Check safety-related optimization settings for Loop unrolling threshold" (Simulink Check)
"hisl_0052: Configuration Parameters > Code Generation > Optimization > Data initialization" on page 5-27	"Check safety-related optimization settings for data initialization" (Simulink Check)
"hisl_0053: Configuration Parameters > Code Generation > Optimization > Remove code from floating-point to integer conversions that wraps out-of-range values" on page 5-29	"Check safety-related optimization settings for data type conversions" (Simulink Check)
"hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions" on page 5-30	"Check safety-related optimization settings for division arithmetic exceptions" (Simulink Check)
"hisl_0056: Configuration Parameters > Code Generation > Optimization > Optimize using the specified minimum and maximum values" on page 5-31	"Check safety-related optimization settings for specified minimum and maximum values" (Simulink Check)
"hisl_0060: Configuration parameters that improve MISRA C:2012 compliance" on page 7-18	"Check configuration parameters for MISRA C:2012" (Simulink Check)
"hisl_0061: Unique identifiers for clarity" on page 7-4	"Check Stateflow charts for uniquely defined data objects" (Simulink Check)
"hisl_0062: Global variables in graphical functions" on page 7-8	"Check global variables in graphical functions" (Simulink Check)
"hisl_0063: Length of user-defined object names to improve MISRA C:2012 compliance" on page 7-10	"Check for length of user-defined object names" (Simulink Check)
"hisl_0066: Usage of Gain blocks" on page 2-14	"Check usage of Gain blocks" (Simulink Check)
"hisl_0070: Placement of requirement links in a model" on page 8-2	"Check for model elements that do not link to requirements" (Simulink Check)

High-Integrity Modeling Guideline	Model Advisor Checks
"hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance" on page 7-14	Not applicable
"hisl_0102: Data type of loop control variables to improve MISRA C:2012 compliance" on page 7-16	"Check data type of loop control variables" (Simulink Check)
"hisl_0301: Configuration Parameters > Diagnostics > Compatibility" on page 5-11	"Check safety-related diagnostic settings for compatibility" (Simulink Check)
"hisl_0302: Configuration Parameters > Diagnostics > Data Validity > Parameters" on page 5-12	"Check safety-related diagnostic settings for parameters" (Simulink Check)
"hisl_0303: Configuration Parameters > Diagnostics > Data Validity > Merge blocks" on page 5-13	"Check safety-related diagnostic settings for Merge blocks" (Simulink Check)
"hisl_0304: Configuration Parameters > Diagnostics > Data Validity > Model initialization" on page 5-14	"Check safety-related diagnostic settings for model initialization" (Simulink Check)
"hisl_0305: Configuration Parameters > Diagnostics > Data Validity > Debugging" on page 5-15	"Check safety-related diagnostic settings for data used for debugging" (Simulink Check)
"hisl_0306: Configuration Parameters > Diagnostics > Connectivity > Signals" on page 5-15	"Check safety-related diagnostic settings for signal connectivity" (Simulink Check)
"hisl_0307: Configuration Parameters > Diagnostics > Connectivity > Buses" on page 5-16	"Check safety-related diagnostic settings for bus connectivity" (Simulink Check)
"hisl_0308: Configuration Parameters > Diagnostics > Connectivity > Function calls" on page 5-17	"Check safety-related diagnostic settings that apply to function-call connectivity" (Simulink Check)
"hisl_0309: Configuration Parameters > Diagnostics > Type Conversion" on page 5-18	"Check safety-related diagnostic settings for type conversions" (Simulink Check)
"hisl_0310: Configuration Parameters > Diagnostics > Model Referencing" on page 5-19	"Check safety-related diagnostic settings for model referencing" (Simulink Check)
"hisl_0311: Configuration Parameters > Diagnostics > Stateflow" on page 5-20	"Check safety-related diagnostic settings for Stateflow" (Simulink Check)
"hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals" on page 5-22	"Check safety-related diagnostic settings for signal data" (Simulink Check)
"hisf_0001: State Machine Type" on page 3-2	"Check state machine type of Stateflow charts" (Simulink Check)

High-Integrity Modeling Guideline	Model Advisor Checks
"hisf_0002: User-specified state/transition execution order" on page 3-3	"Check Stateflow charts for ordering of states and transitions" (Simulink Check)
"hisf_0003: Usage of bitwise operations" on page 3-7	"Check usage of bitwise operations in Stateflow charts" (Simulink Check)
"hisf_0004: Usage of recursive behavior" on page 3-8	Not applicable
"hisf_0007: Usage of junction conditions (maintaining mutual exclusion)" on page 3-9	Not applicable
"hisf_0009: Strong data typing (Simulink and Stateflow boundary)" on page 3-4	
"hisf_0011: Stateflow debugging settings" on page 3-5	"Check Stateflow debugging options" (Simulink Check)
"hisf_0013: Usage of transition paths (crossing parallel state boundaries)" on page 3-10	"Check Stateflow charts for transition paths that cross parallel state boundaries" (Simulink Check)
"hisf_0014: Usage of transition paths (passing through states)" on page 3-12	"Check for inappropriate use of transition paths" (Simulink Check)
"hisf_0015: Strong data typing (casting variables and parameters in expressions)" on page 3-13	"Check Stateflow charts for strong data typing" (Simulink Check)
"hisf_0016: Stateflow port names" on page 3-15	"Check naming of ports in Stateflow charts" (Simulink Check)
"hisf_0017: Stateflow data object scoping" on page 3-16	"Check scoping of Stateflow data objects" (Simulink Check)
"hisf_0064: Shift operations for Stateflow data to improve code compliance" on page 7-20	"Check usage of shift operations for Stateflow data" (Simulink Check)
"hisf_0065: Type cast operations in Stateflow to improve code compliance" on page 7-21	"Check assignment operations in Stateflow Charts" (Simulink Check)
"hisf_0211: Protect against use of unary operators in Stateflow Charts to improve code compliance" on page 7-22	"Check Stateflow charts for unary operators" (Simulink Check)
"hisf_0213: Protect against divide-by-zero calculations in Stateflow charts to improve MISRA C:2012 compliance" on page 7-23	Not applicable

High-Integrity Modeling Guideline	Model Advisor Checks
"himl_0001: Usage of standardized MATLAB function headers" on page 4-2	"Check usage of standardized MATLAB function headers" (Simulink Check)
"himl_0002: Strong data typing at MATLAB function boundaries" on page 4-3	"Check for MATLAB Function interfaces with inherited properties" (Simulink Check)
"himl_0003: Limitation of MATLAB function complexity" on page 4-5	"Check MATLAB Function metrics" (Simulink Check)
"himl_0004: MATLAB Code Analyzer recommendations for code generation" on page 4-8	"Check MATLAB Code Analyzer messages" (Simulink Check)
"himl_0006: MATLAB code if / elseif / else patterns" on page 4-10	"Check if/elseif/else patterns in MATLAB Function blocks" (Simulink Check)
"himl_0007: MATLAB code switch / case / otherwise patterns" on page 4-12	"Check switch statements in MATLAB Function blocks" (Simulink Check)
"himl_0008: MATLAB code relational operator data types" on page 4-14	"Check usage of relational operators in MATLAB Function blocks" (Simulink Check)
"himl_0009: MATLAB code with equal / not equal relational operators" on page 4-16	"Check usage of equality operators in MATLAB Function blocks" (Simulink Check)
"himl_0010: MATLAB code with logical operators and functions" on page 4-17	"Check usage of logical operators and functions in MATLAB Function blocks" (Simulink Check)
"himl_0011: Data type and size of condition expressions" on page 4-19	"Check type and size of condition expressions" (Simulink Check)

Simulink Block Considerations

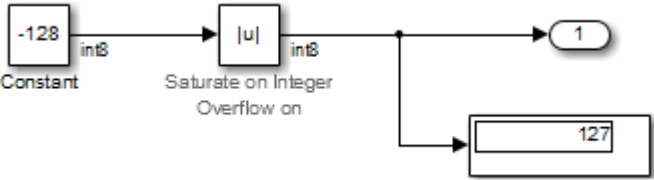
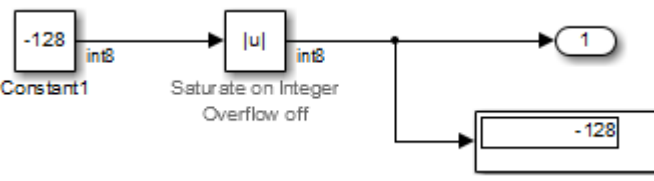
- “Math Operations” on page 2-2
- “Ports & Subsystems” on page 2-16
- “Signal Routing” on page 2-28
- “Logic and Bit Operations” on page 2-38
- “Lookup Table Blocks” on page 2-43

Math Operations

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hisl_0001: Usage of Abs block

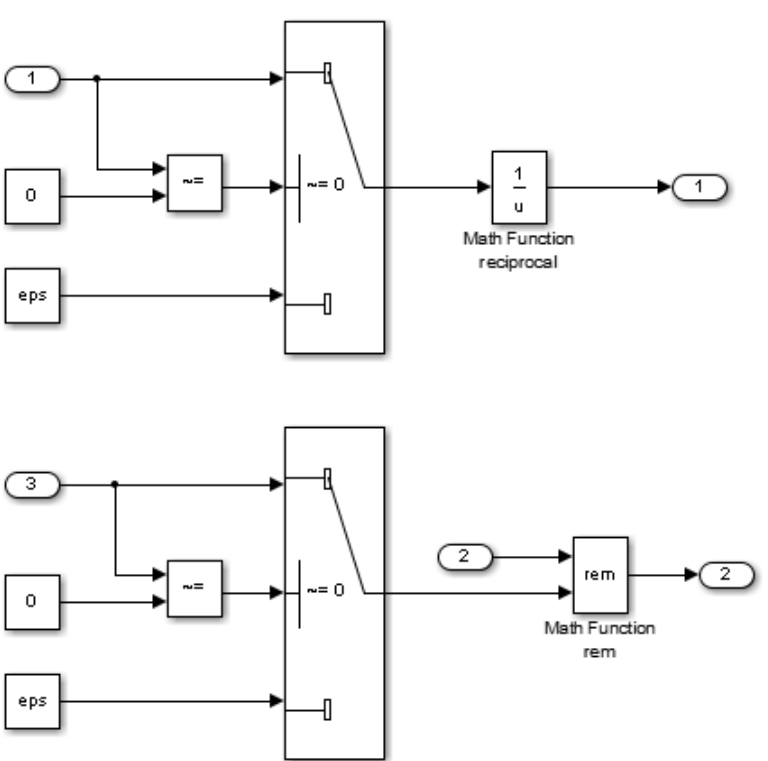
ID: Title	hisl_0001: Usage of Abs block	
Description	To support robustness of generated code, when using the Abs block,	
	A	Avoid Boolean and unsigned data types as inputs to the Abs block.
	B	Select block parameter Saturate on integer overflow .
Notes	<p>The Abs block does not support Boolean data types. Specifying an unsigned input data type, might optimize the Abs block out of the generated code, resulting in a block you cannot trace to the generated code.</p> <p>For signed data types, Simulink does not represent the absolute value of the most negative value. When you select Saturate on integer overflow, the absolute value of the data type saturates to the most positive representable value. When you clear Saturate on integer overflow, absolute value calculations in the simulation and generated code might not be consistent or expected.</p>	
Rationale	A	Support generation of traceable code.
	B	Achieve consistent and expected behavior of model simulation and generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Abs blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Abs blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Abs blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Abs blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Abs blocks <p>For check details, see “Check usage of Abs blocks” (Simulink Check).</p>	

ID: Title	hisl_0001: Usage of Abs block
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table B.8 (3) 'Control Flow Analysis' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • ISO 26262-6, Table 7 (1f) 'Control flow analysis' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.19 (3) 'Control Flow Analysis' • DO-331, Section MB.6.3.2.d 'Low-level requirements are verifiable' • MISRA C:2012, Dir 4.1
Last Changed	R2018b
Examples	 <p>Recommended</p>  <p>Not Recommended</p>

hisl_0002: Usage of Math Function blocks (rem and reciprocal)

ID: Title	hisl_0002: Usage of Math Function blocks (rem and reciprocal)	
Description	To support robustness of generated code, when using the Math Function block with remainder-after-division (rem) or reciprocal (reciprocal) functions:	
	A	Protect the input of the reciprocal function from going to zero.
	B	Protect the second input of the rem function from going to zero.
Note	You can get a divide-by-zero operation, resulting in an infinite (Inf) output value for the reciprocal function, or a Not-a-Number (NaN) output value for the rem function. To avoid overflows or undefined values, protect the corresponding input from going to zero.	
Rationale	Protect against overflows and undefined numerical results.	

ID: Title	hisl_0002: Usage of Math Function blocks (rem and reciprocal)
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (rem and reciprocal functions) • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (rem and reciprocal functions) • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (rem and reciprocal functions) • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (rem and reciprocal functions) • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (rem and reciprocal functions) <p>For check details, see “Check usage of Math Function blocks (rem and reciprocal functions)” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Dir 4.1
Last Changed	R2017b

ID: Title	hisl_0002: Usage of Math Function blocks (rem and reciprocal)
Examples	<p>In the following example, when the input signal oscillates around zero, the output exhibits a large change in value. You need further protection against the large change in value.</p>  <p>The figure contains two Simulink block diagrams. The top diagram shows an input signal '1' and a '0' block feeding into a 'Math Function reciprocal' block. The bottom diagram shows an input signal '3' and a '0' block feeding into a 'Math Function rem' block. Both diagrams include an 'eps' block and a 'Math Function reciprocal' or 'Math Function rem' block.</p>

hisl_0003: Usage of Square Root blocks

ID: Title	hisl_0003: Usage of Square Root blocks	
Description	To support robustness of generated code, when using the Square Root block, do one of the following:	
	A	Account for complex numbers as the output.
	B	Protect the input from going negative.
Rationale	A, B	Avoid undesirable results in generated code.

ID: Title	hisl_0003: Usage of Square Root blocks
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Dir 4.1
Last Changed	R2016a
Examples	<p>The image contains two Simulink block diagrams. The top diagram shows a square root block (√u) with an input of -100. The block's output data type is set to 'Complex'. The output is split into two paths: one leading to a display block showing '2' and another leading to a display block showing '0 + 10i'. The bottom diagram shows an absolute value block (u) with an input of -100, followed by a square root block (√u) with the output data type set to 'Real'. The output is split into two paths: one leading to a display block showing '1' and another leading to a display block showing '10'.</p>

hisl_0028: Usage of Reciprocal Square Root blocks

ID: Title	hisl_0028: Usage of Reciprocal Square Root blocks	
Description	To support robustness of generated code, when using the Reciprocal Square Root block, do one of the following:	
	A	Protect the input from going negative.
	B	Protect the input from going to zero.
Note	You can get a divide-by-zero operation, resulting in an (Inf) output value for the reciprocal function. To avoid overflows or undefined values, protect the corresponding input from going to zero.	
Rationale	A, B	Avoid undesirable results in generated code.

ID: Title	hisl_0028: Usage of Reciprocal Square Root blocks
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Dir 4.1
Last Changed	R2016a
Examples	

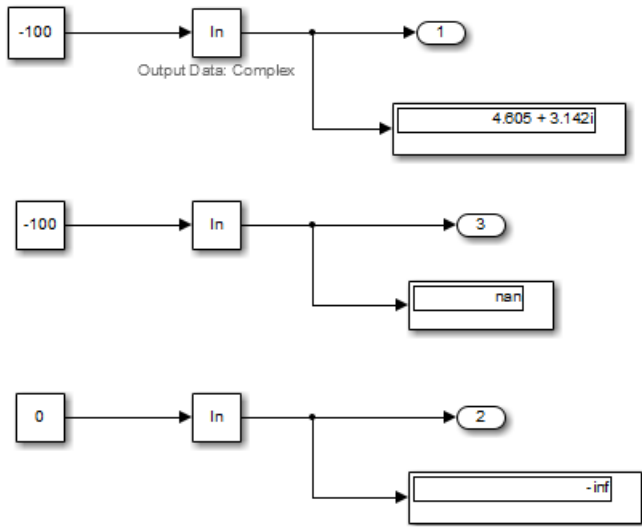
hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)

ID: Title	hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)	
Description	To support robustness of generated code, when using the Math Function block with natural logarithm (\log) or base 10 logarithm (\log_{10}) function parameters,	
	A	Protect the input from going negative.
	B	Protect the input from equalling zero.
	C	Account for complex numbers as the output value.
Notes	If you set the output data type to complex, the natural logarithm and base 10 logarithm functions output complex values for negative input values. If you set the output data type to real, the functions output NAN for negative numbers, and minus infinity ($-\infty$) for zero values.	
Rationale	A, B, C	Support generation of robust code.

ID: Title	hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (log and log10 functions) • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (log and log10 functions) • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (log and log10 functions) • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (log and log10 functions) • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Math Function blocks (log and log10 functions) <p>For check details, see “Check usage of Math Function blocks (log and log10 functions)” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Dir 4.1
Last Changed	R2017b

ID: Title hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)

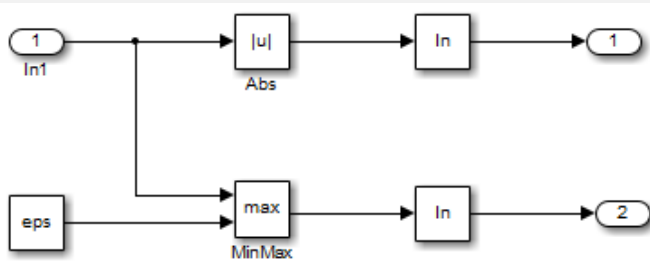
Examples

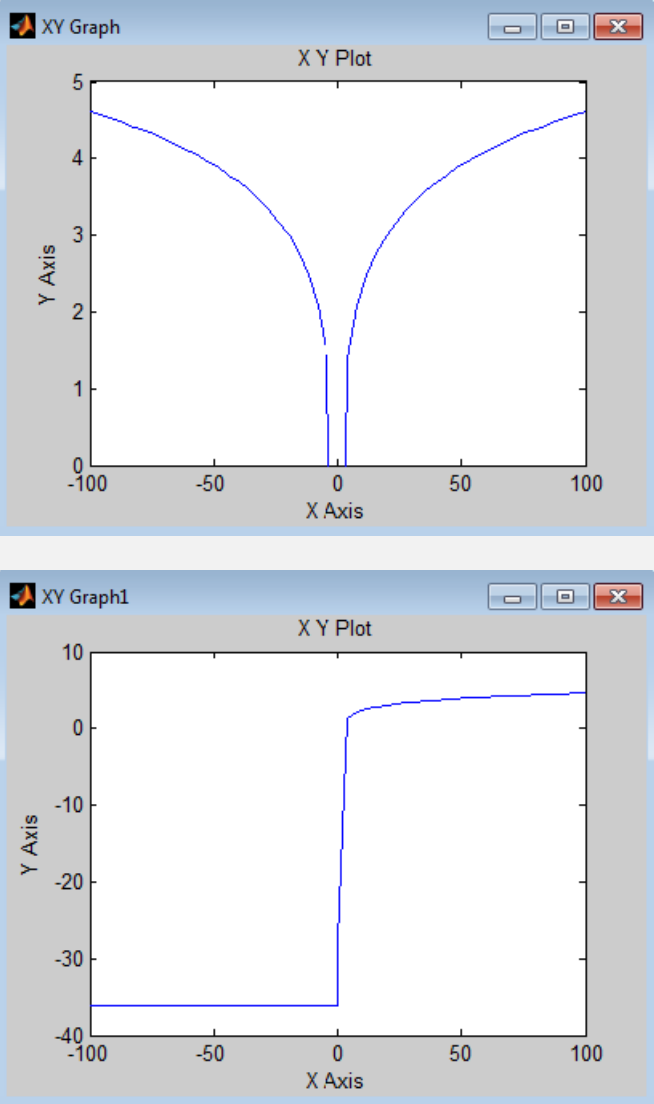


You can protect against:

- Negative numbers using an Abs block.
- Zero values using a combination of the MinMax block and a Constant block, with **Constant value** set to eps (epsilon).

The following example displays the resulting output for input values ranging from -100 to 100.



ID: Title	hisl_0004: Usage of Math Function blocks (natural logarithm and base 10 logarithm)
	 <p>The image displays two Simulink XY Graph windows. The top window, titled 'XY Graph', shows a plot with a vertical asymptote at x=0. The curve approaches positive infinity as x approaches 0 from both sides. The x-axis ranges from -100 to 100, and the y-axis ranges from 0 to 5. The bottom window, titled 'XY Graph1', shows a step function. The y-value is constant at approximately -35 for x < 0 and jumps to approximately 5 for x > 0. The x-axis ranges from -100 to 100, and the y-axis ranges from -40 to 10.</p>

hisl_0005: Usage of Product blocks

ID: Title	hisl_0005: Usage of Product blocks	
Description	To support robustness of generated code, when using the Product block with divisor inputs,	
	A	In Element-wise (.*) mode, protect divisor inputs from going to zero.
	B	In Matrix(*) mode, protect divisor inputs from becoming singular input matrices.

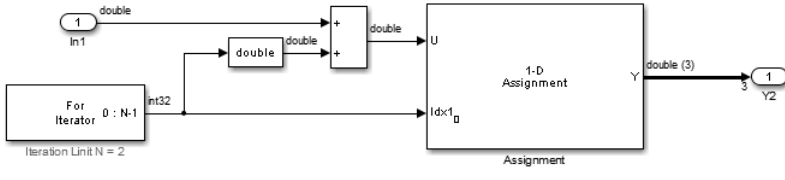
ID: Title	hisl_0005: Usage of Product blocks	
Notes	<p>When using Product blocks for element-wise divisions, you might get a divide by zero, resulting in a NaN output. To avoid overflows, protect divisor inputs from going to zero.</p> <p>When using Product blocks to compute the inverse of a matrix, or a matrix division, you might get a divide by a singular matrix. This division results in a NaN output. To avoid overflows, protect divisor inputs from becoming singular input matrices.</p>	
Rationale	A and B	Protect against overflows.
References	<ul style="list-style-type: none"> IEC 61508-3, Table A.3 (3) 'Language subset' IEC 61508-3, Table A.4 (3) 'Defensive programming' IEC 62304, 5.5.3 - Software Unit acceptance criteria ISO 26262-6, Table 1 (1b) 'Use of language subsets' ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' EN 50128, Table A.4 (11) 'Language Subset' EN 50128, Table A.3 (1) 'Defensive Programming' DO-331, Section MB.6.4.2.2 'Robustness Test Cases' DO-331, Section MB.6.4.3 'Requirements-Based Testing Methods' DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' DO-331, Section MB.6.3.1.g 'Algorithms are accurate' DO-331, Section MB.6.3.2.g 'Algorithms are accurate' DO-331, Section MB.6.3.3.b 'Software architecture is consistent' MISRA C:2012, Dir 4.1 	
Prerequisites	hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals	
Last Changed	R2019a	

hisl_0029: Usage of Assignment blocks

ID: Title	hisl_0029: Usage of Assignment blocks
Description	To support robustness of generated code, when using the Assignment block, initialize array fields before their first use.
Notes	<p>If the output vector of the Assignment block is not initialized with an input to the block, elements of the vector might not be initialized in the generated code.</p> <p>When the Assignment block is used iteratively and all array field are assigned during one simulation time step, you do not need initialization input to the block.</p> <p>Accessing uninitialized elements of block output can result in unexpected behavior.</p>
Rationale	Avoid undesirable results in generated code.

ID: Title	hisl_0029: Usage of Assignment blocks
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Assignment blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Assignment blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Assignment blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Assignment blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Assignment blocks <p>For check details, see “Check usage of Assignment blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • MISRA C:2012, Rule 9.1
Last Changed	R2016a

ID: Title	hisl_0029: Usage of Assignment blocks
Examples	<div data-bbox="402 338 1203 533" data-label="Diagram"> </div> <div data-bbox="370 569 1084 982" data-label="Code-Block"> <pre> 31 /* Model step function */ 32 void Assignment1_step(void) 33 { 34 real T rtb_Assignment[2]; 35 36 /* Assignment: '<Root>/Assignment' incorporates: 37 * Constant: '<Root>/Constant' 38 * Inport: '<Root>/U3' 39 */ 40 rtb_Assignment[0] = Assignment1 U.U3; 41 42 /* Outport: '<Root>/Y2' */ 43 Assignment1 Y.Y2 = rtb_Assignment[1]; 44 } </pre> </div> <p data-bbox="358 1016 1435 1050">Not Recommended: No initialization input Y0 when block is not used iteratively</p> <div data-bbox="418 1150 1138 1367" data-label="Diagram"> </div> <div data-bbox="370 1430 1198 1814" data-label="Code-Block"> <pre> /* Model step function */ 32 void Assignment2_step(void) 33 { 34 /* Assignment: '<Root>/Assignment' incorporates: 35 * Constant: '<Root>/Constant' 36 * Inport: '<Root>/In1' 37 * Inport: '<Root>/In2' 38 */ 39 Assignment2 Y.Y2[0] = 0.0; 40 Assignment2 Y.Y2[1] = 0.0; 41 Assignment2 Y.Y2[2] = 0.0; 42 Assignment2 Y.Y2[Assignment2 U.In2] = Assignment2 U.In1; 43 } </pre> </div> <p data-bbox="358 1848 1338 1881">Recommended: Initialization input Y0 when block is not used iteratively</p>

ID: Title	hisl_0029: Usage of Assignment blocks
	 <pre data-bbox="365 577 1209 1008"> /* Model step function */ 32 void Assignment3_step(void) 33 { 34 int32 T s1_iter; 35 36 /* Outputs for Iterator SubSystem: '<Root>/For Iterator Subsystem' incorporates: 37 * ForIterator: '<SI>/For Iterator' 38 */ 39 for (s1_iter = 0; s1_iter < 2; s1_iter++) { 40 /* Assignment: '<SI>/Assignment' incorporates: 41 * DataTypeConversion: '<SI>/Data Type Conversion' 42 * Inport: '<Root>/In1' 43 * Sum: '<SI>/Add' 44 */ 45 Assignment3_Y.Out1[s1_iter] = Assignment3_U.In1 + ((real T)s1_iter); 46 } 47 48 /* End of Outputs for SubSystem: '<Root>/For Iterator Subsystem' */ 49 } </pre> <p data-bbox="365 1039 1266 1071">Recommended: Initialize array fields when block is used iteratively</p>

hisl_0066: Usage of Gain blocks

ID: Title	hisl_0066: Usage of Gain blocks
Description	To support traceability of generated code, the value of the Gain block must not resolve to 1.
Notes	<p>The code generation process can remove Gain values equal to 1 during optimization, resulting in model elements with no traceable code.</p> <p>An exception to this rule is setting the Gain value to a named parameter data object with a non-auto storage class.</p>
Rationale	Support the generation of traceable code.

ID: Title	hisl_0066: Usage of Gain blocks
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Gain blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Gain blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Gain blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Gain blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Gain blocks <p>For check details, see “Check usage of Gain blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.d 'Low-level requirements are verifiable' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 61508-3, Table B.8 (3) 'Control Flow Analysis' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • ISO 26262-6, Table 7 (1f) 'Control flow analysis' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • EN 50128, Table A.19 (3) 'Control Flow Analysis'
Last Changed	R2018a

Ports & Subsystems

In this section...
“hisl_0006: Usage of While Iterator blocks” on page 2-16
“hisl_0007: Usage of For Iterator or While Iterator subsystems” on page 2-17
“hisl_0008: Usage of For Iterator Blocks” on page 2-18
“hisl_0010: Usage of If blocks and If Action Subsystem blocks” on page 2-19
“hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks” on page 2-21
“hisl_0012: Usage of conditionally executed subsystems” on page 2-23
“hisl_0024: Inport interface definition” on page 2-24
“hisl_0025: Design min/max specification of input interfaces” on page 2-25
“hisl_0026: Design min/max specification of output interfaces” on page 2-26

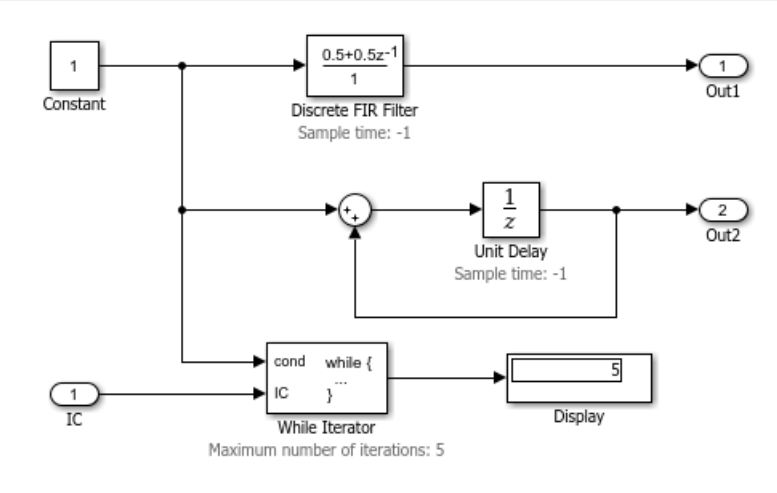
hisl_0006: Usage of While Iterator blocks

ID: Title	hisl_0006: Usage of While Iterator blocks
Description	To support bounded iterative behavior in the generated code when using the While Iterator block, set block parameter Maximum number of iterations to a positive integer value.
Note	<p>When you use While Iterator subsystems, set the maximum number of iterations. If you use an unlimited number of iterations, the generated code might include infinite loops, which lead to execution-time overruns.</p> <p>To observe the iteration value during simulation and determine whether the loop reaches the maximum number of iterations, select the While Iterator block parameter Show iteration number port. If the loop reaches the maximum number of iterations, verify the output values of the While Iterator block.</p>
Rationale	Support bounded iterative in the generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of While Iterator blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of While Iterator blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of While Iterator blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of While Iterator blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of While Iterator blocks <p>For check details, see “Check usage of While Iterator blocks” (Simulink Check).</p>

ID: Title	hisl_0006: Usage of While Iterator blocks
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 14.2 • MISRA C:2012, Rule 16.4 • MISRA C:2012, Dir 4.1
Last Changed	R2018b

hisl_0007: Usage of For Iterator or While Iterator subsystems

ID: Title	hisl_0007: Usage of For Iterator or While Iterator subsystems
Description	To support unambiguous behavior, when using For Iterator Subsystem or While Iterator Subsystem, avoid using sample time-dependent blocks, such as integrators, filters, and transfer functions within the subsystems.
Rationale	Avoid ambiguous behavior from the subsystem.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of For and While Iterator subsystems • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of For and While Iterator subsystems • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of For and While Iterator subsystems • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of For and While Iterator subsystems • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of For and While Iterator subsystems <p>For check details, see "Check usage of For and While Iterator subsystems" (Simulink Check).</p>

ID: Title	hisl_0007: Usage of For Iterator or While Iterator subsystems
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 14.2 • MISRA C:2012, Rule 16.4 • MISRA C:2012, Dir 4.1
Last Changed	R2018b
Examples	<p>The following example causes a warning: the Discrete FIR Filter block is time-dependent and is in a For or While Iterator subsystem.</p>  <p>The diagram shows a Simulink model where a 'While Iterator' block (with 'Maximum number of iterations: 5') contains three sub-blocks: a 'Discrete FIR Filter' (with transfer function $\frac{0.5+0.5z^{-1}}{1}$ and 'Sample time: -1'), a 'Unit Delay' (with transfer function $\frac{1}{z}$ and 'Sample time: -1'), and a 'Display' block showing the value '5'. The FIR filter's output is summed with the input of the unit delay, and the result is fed back into the FIR filter. The output of the unit delay is labeled 'Out2'. A 'Constant' block with value '1' is also connected to the FIR filter's input.</p>

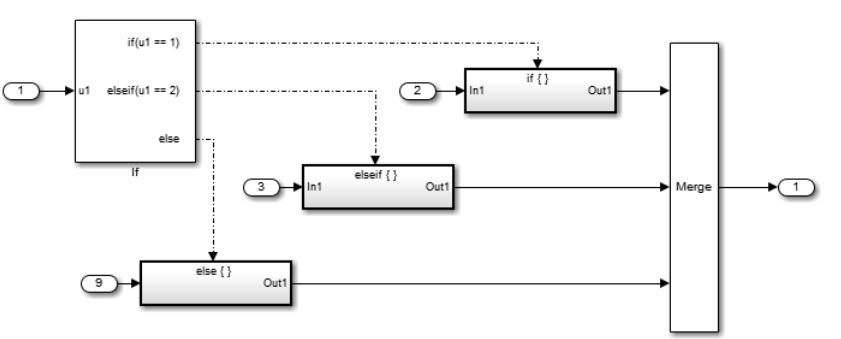
hisl_0008: Usage of For Iterator Blocks

ID: Title	hisl_0008: Usage of For Iterator blocks								
Description	<p>To support bounded iterative behavior in the generated code when using the For Iterator block, do one of the following:</p> <table border="1" data-bbox="401 1640 1472 1871"> <tr> <td data-bbox="401 1640 493 1682">A</td> <td data-bbox="493 1640 1472 1682">Set block parameter Iteration limit source to internal.</td> </tr> <tr> <td data-bbox="401 1682 493 1759">B</td> <td data-bbox="493 1682 1472 1759">When Iteration limit source must be external, use a block that has a constant value. Options include Width, Probe, or Constant.</td> </tr> <tr> <td data-bbox="401 1759 493 1801">C</td> <td data-bbox="493 1759 1472 1801">Clear block parameters Set next i (iteration variable) externally.</td> </tr> <tr> <td data-bbox="401 1801 493 1871">D</td> <td data-bbox="493 1801 1472 1871">To observe the iteration value during simulation, select block parameter Show iteration variable.</td> </tr> </table>	A	Set block parameter Iteration limit source to internal .	B	When Iteration limit source must be external , use a block that has a constant value. Options include Width, Probe, or Constant.	C	Clear block parameters Set next i (iteration variable) externally .	D	To observe the iteration value during simulation, select block parameter Show iteration variable .
A	Set block parameter Iteration limit source to internal .								
B	When Iteration limit source must be external , use a block that has a constant value. Options include Width, Probe, or Constant.								
C	Clear block parameters Set next i (iteration variable) externally .								
D	To observe the iteration value during simulation, select block parameter Show iteration variable .								

ID: Title	hisl_0008: Usage of For Iterator blocks	
Notes	When you use the For Iterator block, feed the loop control variable with fixed (nonvariable) values to get a predictable number of loop iterations. Otherwise, a loop can result in unpredictable execution times and, in the case of external iteration variables, infinite loops that can lead to execution-time overruns.	
Rationale	A, B, C, D	Support bounded iterative behavior in generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of For Iterator blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of For Iterator blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of For Iterator blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of For Iterator blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of For Iterator blocks <p>For check details, see “Check usage of For Iterator blocks” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, MB.Section 6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 14.2 • MISRA C:2012, Rule 16.4 • MISRA C:2012, Dir 4.1 	
Last Changed	R2016a	

hisl_0010: Usage of If blocks and If Action Subsystem blocks

ID: Title	hisl_0010: Usage of If blocks and If Action Subsystem blocks	
Description	To support verifiable generated code, when using the If block with nonempty Elseif expressions,	
	A	Select block parameter Show else condition .
	B	Connect the outports of the If block to If Action Subsystem blocks.
Prerequisites	“hisl_0016: Usage of blocks that compute relational operators” on page 2-38	
Notes	The combination of If and If Action Subsystem blocks enable conditional execution based on input conditions. When there is only an if branch, you do not need to include an else branch.	

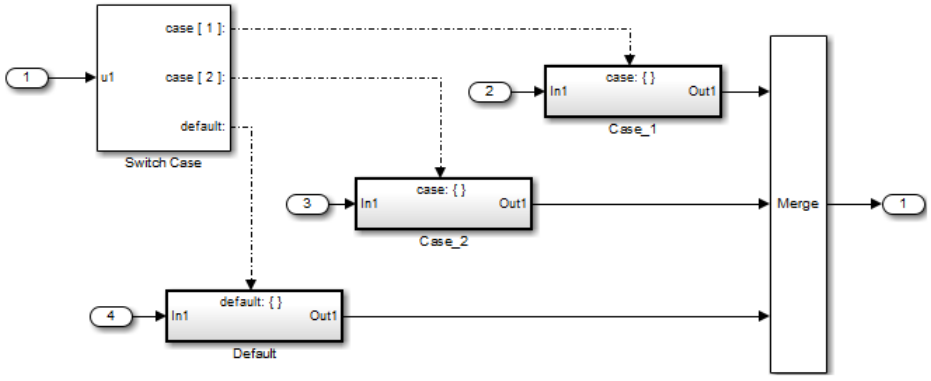
ID: Title	hisl_0010: Usage of If blocks and If Action Subsystem blocks
Rationale	A, B Support generation of verifiable code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of If blocks and If Action Subsystem blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of If blocks and If Action Subsystem blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of If blocks and If Action Subsystem blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of If blocks and If Action Subsystem blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of If blocks and If Action Subsystem blocks <p>For check details, see “Check usage of If blocks and If Action Subsystem blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate' • DO-331 Section MB.6.3.1.b - High-level requirements are accurate and consistent • DO-331 Section MB.6.3.2.b - Low-level requirements are accurate and consistent • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 14.2 • MISRA C:2012, Rule 16.4 • MISRA C:2012, Dir 4.1
Last Changed	R2016b
Examples	 <p>Recommended: Elseif with Else</p>

ID: Title	hisl_0010: Usage of If blocks and If Action Subsystem blocks
	<div data-bbox="414 304 1250 577" style="border: 1px solid black; padding: 5px;"> <p>The diagram shows a flow starting with input '4' entering an 'if(u1 == 1) elseif(u1 == 2)' block. Two dashed arrows branch out: one to an 'if {}' block (input '5') and one to an 'elseif {}' block (input '6'). Both 'if {}' and 'elseif {}' blocks have 'Out1' ports that connect to a vertical 'Merge' block. The output of the 'Merge' block is '2'.</p> </div> <p data-bbox="406 609 844 640">Not Recommended: No Else Path</p> <div data-bbox="414 661 1153 871" style="border: 1px solid black; padding: 5px;"> <p>The diagram shows a flow starting with input '7' entering an 'if(u1 == 1)' block. A dashed arrow leads to an 'if {}' block (input '8'). The 'if {}' block has an 'Out1' port that leads to output '3'.</p> </div> <p data-bbox="406 892 990 924">Recommended: Only an If, no Else required</p>

hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks

ID: Title	hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks	
Description	To support verifiable generated code, when using the Switch Case block:	
A	Select block parameter Show default case .	
B	Connect the outputs of the Switch Case block to a Switch Case Action Subsystem block.	
C	Use an integer data type or an enumeration value for the inputs to Switch Case blocks.	
Prerequisites	"hisl_0016: Usage of blocks that compute relational operators" on page 2-38	
Notes	The combination of Switch Case and If Action Subsystem blocks enable conditional execution based on input conditions. Provide a default path of execution in the form of a "Default" block.	
Rationale	A, B, C Support generation of verifiable code.	

ID: Title	hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Switch Case blocks and Switch Case Action Subsystem blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Switch Case blocks and Switch Case Action Subsystem blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Switch Case blocks and Switch Case Action Subsystem blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Switch Case blocks and Switch Case Action Subsystem blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Switch Case blocks and Switch Case Action Subsystem blocks <p>For check details, see “Check usage of Switch Case blocks and Switch Case Action Subsystem blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate' • DO-331 Section MB.6.3.1.b - High-level requirements are accurate and consistent • DO-331 Section MB.6.3.2.b - Low-level requirements are accurate and consistent • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 14.2 • MISRA C:2012, Rule 16.4 • MISRA C:2012, Dir 4.1
Last Changed	R2016b

ID: Title	hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks
Examples	<p>The following graphic displays an example of providing a default path of execution using a “Default” block.</p> 

hisl_0012: Usage of conditionally executed subsystems

ID: Title	hisl_0012: Usage of conditionally executed subsystems					
Description	<p>To support unambiguous behavior, when using conditionally executed subsystems:</p> <table border="1" data-bbox="402 982 1474 1159"> <tr> <td data-bbox="402 982 493 1024">A</td> <td data-bbox="493 982 1474 1060">Specify inherited (- 1) sample times for all blocks in the subsystem, except Constant. Constant blocks can use infinite (inf) sample time.</td> </tr> <tr> <td data-bbox="402 1060 493 1159">B</td> <td data-bbox="493 1060 1474 1159">If the subsystem is called asynchronously, avoid using sample time-dependent blocks, such as integrators, filters, and transfer functions, within the subsystem.</td> </tr> </table>		A	Specify inherited (- 1) sample times for all blocks in the subsystem, except Constant. Constant blocks can use infinite (inf) sample time.	B	If the subsystem is called asynchronously, avoid using sample time-dependent blocks, such as integrators, filters, and transfer functions, within the subsystem.
A	Specify inherited (- 1) sample times for all blocks in the subsystem, except Constant. Constant blocks can use infinite (inf) sample time.					
B	If the subsystem is called asynchronously, avoid using sample time-dependent blocks, such as integrators, filters, and transfer functions, within the subsystem.					
Rationale	A, B	Support unambiguous behavior.				
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of conditionally executed subsystems • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of conditionally executed subsystems • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of conditionally executed subsystems • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of conditionally executed subsystems • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of conditionally executed subsystems <p>For check details, see “Check usage of conditionally executed subsystems” (Simulink Check).</p>					

ID: Title	hisl_0012: Usage of conditionally executed subsystems
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate'
Last Changed	R2018b
Examples	When using discrete blocks, the behavior depends on the operation across multiple contiguous time steps. When the blocks are called intermittently, the results may not conform to your expectations.

hisl_0024: Inport interface definition

ID: Title	hisl_0024: Inport interface definition
Description	<p>To support strong data typing and unambiguous behavior of the model and the generated code, for each root-level Inport block or Simulink signal object that explicitly resolves to the connected signal line, set the following parameters:</p> <ul style="list-style-type: none"> • Data type • Port dimensions • Sample time
Note	Using root-level Inport blocks without fully defined dimensions, sample times, or data type can lead to ambiguous simulation results. If you do not explicitly define these parameters, Simulink back-propagates dimensions, sample times, and data types from downstream blocks.
Rationale	<ul style="list-style-type: none"> • Avoid unambiguous behavior. • Support full specification of software interface.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for root Inports with missing properties • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for root Inports with missing properties • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for root Inports with missing properties • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for root Inports with missing properties • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for root Inports with missing properties <p>For check details, see “Check for root Inports with missing properties” (Simulink Check).</p>

ID: Title	hisl_0024: Inport interface definition
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table B.9 (6) 'Fully defined interface' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1a) - Enforcement of low complexity • ISO 26262-6, Table 1 (1c) - Enforcement of strong typing • ISO 26262-6, Table 1 (1f) - Use of unambiguous graphical representation • ISO 26262-6, Table 3 (1c) - Restricted size of interfaces • ISO 26262-6, Table 7 (1k) - Interface test • EN 50128, Table A.3 (19) 'Fully Defined Interface'
Last Changed	R2017b

hisl_0025: Design min/max specification of input interfaces

ID: Title	hisl_0025: Design min/max specification of input interfaces
Description	Provide design min/max information for root-level Inport blocks to specify the input interface ranges.
Notes	<ul style="list-style-type: none"> • Specifying the range of Inport blocks on the root level enables additional capabilities^aExamples include: <ul style="list-style-type: none"> • Detection of overflows through simulation range checking. • Code optimizations using Embedded Coder. • Design model verification using Simulink Design Verifier™. • Fixed-point autoscaling using Fixed-Point Designer™. • Specified design ranges are used by Embedded Coder to optimize the generated code. To use these design ranges for optimization, select configuration parameter Optimize using the specified minimum and maximum values. This configuration parameter is applicable only when the System target file is an ERT-based target. • Ranges for bus-type Inport blocks are specified with the bus elements of the defining bus object. Simulink ignores range specifications provided directly at Inport blocks that are bus-type.
Rationale	Support precise specification of the input interface.

ID: Title	hisl_0025: Design min/max specification of input interfaces
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for root Inports with missing range definitions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for root Inports with missing range definitions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for root Inports with missing range definitions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for root Inports with missing range definitions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for root Inports with missing range definitions <p>For check details, see “Check for root Inports with missing range definitions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table B.9 (6) 'Fully defined interface' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 7 (1e) - Formal verification • ISO 26262-6, Table 7 (1k) - Interface test • ISO 26262-6, Table 8 (1c) - Analysis of boundary values • EN 50128, Table A.1(11) - Software Interface Specifications • EN 50128 Table A.3 (19) 'Fully Defined Interface'
Last Changed	R2017b

a. These capabilities leverage design range information for different purposes. For more information, refer to the documentation for the tools you intend to use.

hisl_0026: Design min/max specification of output interfaces

ID: Title	hisl_0026: Design min/max specification of output interfaces
Description	Provide design min/max information for root-level Outport blocks to specify the output interface ranges.

ID: Title	hisl_0026: Design min/max specification of output interfaces
Notes	<ul style="list-style-type: none"> • Specifying the range of Outport blocks on the root level enables additional capabilities^aExamples include: <ul style="list-style-type: none"> • Detection of overflows through simulation range checking. • Code optimizations using Embedded Coder. • Design model verification using Simulink Design Verifier. • Fixed-point autoscaling using Fixed-Point Designer. • Specified design ranges are used by Embedded Coder to optimize the generated code. To set these design ranges, select configuration parameter Optimize using the specified minimum and maximum values. This configuration parameters is applicable only when the System target file is an ERT-based target. • Ranges for bus-type Outport blocks are specified with the bus elements of the defining bus object. Simulink ignores range specifications provided directly at Outport blocks that are bus-type.
Rationale	Support precise specification of the output interface.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for root Outports with missing range definitions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for root Outports with missing range definitions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for root Outports with missing range definitions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for root Outports with missing range definitions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for root Outports with missing range definitions <p>For check details, see “Check for root Outports with missing range definitions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table B.9 (6) 'Fully defined interface' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 7 (1e) - Formal verification • ISO 26262-6, Table 7 (1k) - Interface test • ISO 26262-6, Table 8 (1c) - Analysis of boundary values • EN 50128, Table A.1(11) - Software Interface Specifications • EN 50128 Table A.3 (19) 'Fully Defined Interface'
Last Changed	R2017b

- a. These capabilities leverage design range information for different purposes. For more information, refer to the documentation for the tools you intend to use.




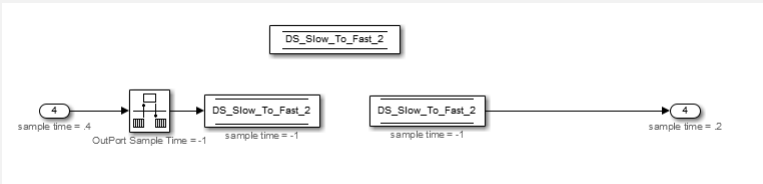
Signal Routing

In this section...
"hisl_0013: Usage of data store blocks" on page 2-28
"hisl_0015: Usage of Merge blocks" on page 2-30
"hisl_0021: Consistent vector indexing method" on page 2-32
"hisl_0022: Data type selection for index signals" on page 2-34
"hisl_0023: Verification of model and subsystem variants" on page 2-35
"hisl_0034: Usage of Signal Routing blocks" on page 2-36

hisl_0013: Usage of data store blocks

ID: Title	hisl_0013: Usage of data store blocks	
Description	To support deterministic behavior across different sample times or models when using data store blocks, including Data Store Memory, Data Store Read, and Data Store Write:	
	A	In the Configuration Parameters dialog box, on the Diagnostics > Data Validity pane, set the Data Store Memory block parameters to error: <ul style="list-style-type: none"> • Detect read before write • Detect write after read • Detect write after write • Multitask data store • Duplicate data store names
	B	Avoid data store reads and writes that occur across model and atomic subsystem boundaries.
	C	Avoid using data stores to write and read data at different rates, because different rates can result in inconsistent exchanges of data. To provide deterministic data coupling in multirate systems, use Rate Transition blocks before Data Store Write blocks, or after Data Store Read blocks.
Notes	<p>The sorting algorithm in Simulink does not take into account data coupling between models and atomic subsystems.</p> <p>Using data store memory blocks can have significant impact on your software verification effort. Models and subsystems that use only inports and outports to pass data provide a directly traceable interface, simplifying the verification process.</p>	
Rationale	A, B, C	Support consistent data values across different sample times or models.

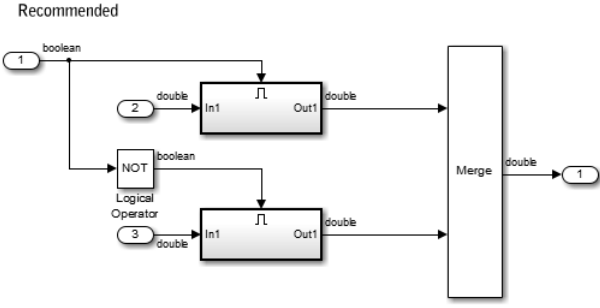
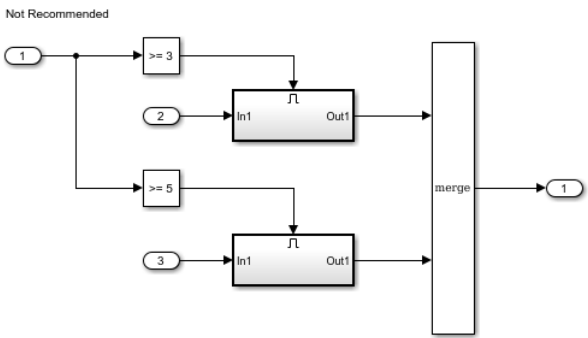
ID: Title	hisl_0013: Usage of data store blocks
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data store memory • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data store memory • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Configuration > Check safety-related diagnostic settings for data store memory • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Configuration > Check safety-related diagnostic settings for data store memory • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Configuration > Check safety-related diagnostic settings for data store memory <p>For more details, see “Check safety-related diagnostic settings for data store memory” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent'
Last Changed	R2017b

ID: Title	hisl_0013: Usage of data store blocks
Examples	<p>The following examples use Rate Transition blocks to provide deterministic data coupling in multirate systems</p> <ul style="list-style-type: none"> For fast-to-slow transitions: <p>Set the rate of the slow sample time on either the Rate Transition block or the Data Store Write block.</p>  <p>Do not place the Rate Transition block after the Data Store Read block.</p>  For slow-to-fast transitions: <p>If the Rate Transition block is after the Data Store Read block, specify the slow rate on the Data Store Read block.</p>  <p>If the Rate Transition block is before the Data Store Write block, use the inherited sample time for the blocks.</p> 

hisl_0015: Usage of Merge blocks

ID: Title	hisl_0015: Usage of Merge blocks	
Description	To support unambiguous behavior from Merge blocks,	
A		Use Merge blocks only with conditionally executed subsystems.
B		Specify execution of the conditionally executed subsystems such that only one subsystem executes during a time step.

ID: Title	hisl_0015: Usage of Merge blocks	
	C	Clear block parameter Allow unequal port widths .
	D	Set the Outport block parameter Output when disabled to held for each conditionally executed subsystem being merged.
Notes	<p>Simulink combines the inputs of the Merge block into a single output. The output value at any time is equal to the most recently computed output of the blocks that drive the Merge block. Therefore, the Merge block output is dependent upon the execution order of the input computations.</p> <p>To provide predictable behavior of the Merge block output, you must have mutual exclusion between the conditionally executed subsystems feeding a Merge block.</p> <p>Merge block parameter Allow unequal port widths is only available when configuration parameter Underspecified initialization detection is set to Classic.</p>	
Prerequisites	<p>hisl_0303: Configuration Parameters > Diagnostics > Merge block</p> <p>hisl_0304: Configuration Parameters > Diagnostics > Model initialization</p>	
Rationale	A, B, C, D	Avoid unambiguous behavior.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Merge blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Merge blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Merge blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Merge blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Merge blocks <p>For check details, see “Check usage of Merge blocks” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' 	
See Also	Merge block in the Simulink documentation	
Last Changed	R2018b	

ID: Title	hisl_0015: Usage of Merge blocks
Examples	<div style="border: 1px solid black; padding: 10px;"> <p style="text-align: center;">Recommended</p>  <p style="text-align: center;">Recommended</p> <p style="text-align: center;">Not Recommended</p>  <p style="text-align: center;">Not Recommended</p> </div>

hisl_0021: Consistent vector indexing method

ID: Title	hisl_0021: Consistent vector indexing method
Description	Within a model, use:

ID: Title	hisl_0021: Consistent vector indexing method	
	A	<p>Consistent vector indexing method.</p> <p>Supports configurable indexing:</p> <ul style="list-style-type: none"> • Assignment • For Iterator • Index Vector • Multiport Switch • Selector <p>Support only one-based indexing:</p> <ul style="list-style-type: none"> • Fcn (deprecated) • MATLAB Function • MATLAB System • State Transition Table • Test Sequence • Truth Table • Stateflow chart with MATLAB action language • Truth Table function with MATLAB action language <p>Supports only zero-based indexing:</p> <ul style="list-style-type: none"> • Stateflow chart with C action language • Truth Table function with C action language
Rationale	A	Reduce the risk of introducing errors due to inconsistent indexing.
Model Advisor Checks		<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for inconsistent vector indexing methods • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for inconsistent vector indexing methods • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for inconsistent vector indexing methods • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for inconsistent vector indexing methods • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for inconsistent vector indexing methods <p>For check details, see “Check for inconsistent vector indexing methods” (Simulink Check).</p>

ID: Title	hisl_0021: Consistent vector indexing method
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (5) 'Design and coding standards' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1e) 'Use of well-trusted design principles' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1g) 'Use of style guide' • ISO 26262-6, Table 1 (1h) 'Use of naming conventions' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.12 (1) 'Coding Standard' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent'
See Also	"cgsl_0101: Zero-based indexing"
Last Changed	R2019a

hisl_0022: Data type selection for index signals

ID: Title	hisl_0022: Data type selection for index signals	
Description	For index signals, use:	
	A	An integer or enumerated data type
	B	A data type that covers the range of indexed values.
Rationale	Blocks that use a signal index include:	
	<ul style="list-style-type: none"> • Assignment • Direct Lookup Table (n-D) • Index Vector • Interpolation Using Prelookup • MATLAB® Function • Multiport Switch • Selector • Stateflow® Chart 	
Rationale	A	Prevent unexpected results that can occur with rounding operations for floating-point data types.
	B	Enable access to data in a vector.

ID: Title	hisl_0022: Data type selection for index signals
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check data types for blocks with index signals • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check data types for blocks with index signals • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check data types for blocks with index signals • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check data types for blocks with index signals • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check data types for blocks with index signals <p>For check details, see “Check data types for blocks with index signals” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.4.f 'Accuracy and Consistency of Source Code'
Last Changed	R2018b

hisl_0023: Verification of model and subsystem variants

ID: Title	hisl_0023: Verification of model and subsystem variants	
Description	When verifying that a model is consistent with generated code, do the following:	
	A	For each Model Variant block, clear block parameter Generate preprocessor conditionals .
	B	For each Variant Subsystem block, clear block parameter Analyze all choices during update diagram and generate preprocessor conditionals .
	C	Verify combinations of model variants that might be active in the generated code.
Rationale	A,B	Simplify consistency testing between the model and generated code by restricting the code base to a single variant.
	C	Verify that consistency testing between the model and generated code is complete for variants.

ID: Title	hisl_0023: Verification of model and subsystem variants
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for variant blocks with 'Generate preprocessor conditionals' active • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for variant blocks with 'Generate preprocessor conditionals' active • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for variant blocks with 'Generate preprocessor conditionals' active • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for variant blocks with 'Generate preprocessor conditionals' active • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for variant blocks with 'Generate preprocessor conditionals' active <p>For check details, see “Check for variant blocks with 'Generate preprocessor conditionals' active” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.4 (7) 'Use of trusted / verified software modules and components'
Last Changed	R2017b

hisl_0034: Usage of Signal Routing blocks

ID: Title	hisl_0034: Usage of Signal Routing blocks
Description	When using Switch blocks, avoid comparisons using the ~= operator on floating-point data types.
Note	<p>Due to floating-point precision issues, do not test floating-point expressions for inequality (~=).</p> <p>When the model contains a Switch block computing a relational operator with the ~= operator, the inputs to the block must not be single, double, or any custom storage class that is a floating-point type. Change the data type of the input signals, or rework the model to eliminate using the ~= operator within Switch blocks.</p>
Rationale	Improve model robustness.

ID: Title	hisl_0034: Usage of Signal Routing blocks
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Signal Routing blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Signal Routing blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Signal Routing blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Signal Routing blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Signal Routing blocks <p>For check details, see “Check usage of Signal Routing blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (3) - 'Language subset' Table A.4 (3) - 'Defensive programming' • IEC 62304, 5.5.3 - 'Software Unit acceptance criteria' • ISO 26262-6, Table 1 (1b) - 'Use of language subsets' Table 1 (1d) - 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) - 'Language Subset' Table A.3 (1) - 'Defensive Programming' • MISRA C:2012, Dir 1.1
Last Changed	R2017b

Logic and Bit Operations

In this section...

“hisl_0016: Usage of blocks that compute relational operators” on page 2-38

“hisl_0017: Usage of blocks that compute relational operators (2)” on page 2-39

“hisl_0018: Usage of Logical Operator block” on page 2-40

“hisl_0019: Usage of bitwise operations” on page 2-41

hisl_0016: Usage of blocks that compute relational operators

ID: Title	hisl_0016: Usage of blocks that compute relational operators	
Description	To support the robustness of the operations, when using blocks that compute relational operators, including Relational Operator, Compare To Constant, Compare To Zero, Detect Change, and If blocks:	
	A	Avoid comparisons using the == or ~= operator on floating-point data types.
Notes	<p>Due to floating-point precision issues, do not test floating-point expressions for equality (==) or inequality (~=).</p> <p>When the model contains a block computing a relational operator with the == or ~= operators, the inputs to the block must not be single, double, or any custom storage class that is a floating-point type. Change the data type of the input signals, or rework the model to eliminate using the == or ~= operators within blocks that compute relational operators.</p>	
Rationale	A	Improve model robustness.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for Relational Operator blocks that equate floating-point types • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for Relational Operator blocks that equate floating-point types • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for Relational Operator blocks that equate floating-point types • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for Relational Operator blocks that equate floating-point types • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for Relational Operator blocks that equate floating-point types <p>For check details, see “Check for Relational Operator blocks that equate floating-point types” (Simulink Check).</p>	

ID: Title	hisl_0016: Usage of blocks that compute relational operators
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Dir 1.1
See Also	"hisl_0017: Usage of blocks that compute relational operators (2)" on page 2-39
Last Changed	R2018a
Examples	<p>Positive Pattern: To test whether two floating-point variables or expressions are equal, compare the difference of the two variables against a threshold that takes into account the floating-point relative accuracy (<i>eps</i>) and the magnitude of the numbers.</p> <p>The following pattern shows how to test two double-precision input signals, In1 and In2, for equality.</p>

hisl_0017: Usage of blocks that compute relational operators (2)

ID: Title	hisl_0017: Usage of blocks that compute relational operators (2)	
Description	To support unambiguous behavior in the generated code, when using blocks that compute relational operators, including Relational Operator, Compare To Constant, Compare to Zero, and Detect Change	
A	Set block parameter Output data type to Boolean.	
B	For Relational Operator blocks, verify that input signals are of the same data type.	
Rationale	A, B Support generation of code that produces unambiguous behavior.	

ID: Title	hisl_0017: Usage of blocks that compute relational operators (2)
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Relational Operator blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Relational Operator blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Relational Operator blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Relational Operator blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Relational Operator blocks <p>For check details, see “Check usage of Relational Operator blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Rule 10.1
See Also	“hisl_0016: Usage of blocks that compute relational operators” on page 2-38
Last Changed	R2018a

hisl_0018: Usage of Logical Operator block

ID: Title	hisl_0018: Usage of Logical Operator block	
Description	To support unambiguous behavior of generated code, when using the Logical Operator block,	
	A	Set block parameter Output data type to Boolean.
	B	Ensure input signals are of type Boolean.
Prerequisites	“hisl_0045: Configuration Parameters > Math and Data Types > Implement logic signals as Boolean data (vs. double)” on page 5-5	
Rationale	A, B	Avoid ambiguous behavior of generated code.

ID: Title	hisl_0018: Usage of Logical Operator block
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of Logical Operator blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of Logical Operator blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of Logical Operator blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of Logical Operator blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of Logical Operator blocks <p>For check details, see “Check usage of Logical Operator blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.e—High-level requirements conform to standards • DO-331, Section MB.6.3.2.e—Low-level requirements conform to standards • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • DO-331, Section MB.6.3.4.e—Source code is traceable to low-level requirements. • DO-331, Section MB.6.3.3.b—Software architecture is consistent. • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Directive 10.1
Last Changed	R2017b

hisl_0019: Usage of bitwise operations

ID: Title	hisl_0019: Usage of bitwise operations	
Description	To support unambiguous behavior, when using bitwise operations in Simulink blocks,	
	A	Avoid signed data types as input to the block.

ID: Title	hisl_0019: Usage of bitwise operations	
Notes	<p>Bitwise operations on signed data types are not meaningful. If a shift operation moves a signed bit into a numeric bit, or a numeric bit into a signed bit, unpredictable and unwanted behavior can result.</p> <p>Bitwise blocks include:</p> <ul style="list-style-type: none"> • Bit Clear • Bit Set • Bitwise Operator • Extract Bits • Shift Arithmetic 	
Rationale	A	Support unambiguous behavior of generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for bitwise operations in Simulink blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for bitwise operations in Simulink blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for bitwise operations in Simulink blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for bitwise operations in Simulink blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for bitwise operations in Simulink blocks <p>For check details, see “Check usage of bit operation blocks” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • MISRA C:2012, Rule 10.1 	
See Also	“hisf_0003: Usage of bitwise operations” on page 3-7in the Simulink documentation	
Last Changed	R2019a	

Lookup Table Blocks

hisl_0033: Usage of Lookup Table blocks

ID: Title	hisl_0033: Usage of Lookup Table blocks	
Description	To support robustness of generated code, when using the 1-D Lookup Table, 2-D Lookup Table, n-D Lookup Table, Prelookup, and Interpolation Using Prelookup blocks:	
	A	Clear block parameter Remove protection against out-of-range input in generated code in each 1-D Lookup Table, 2-D Lookup Table, n-D Lookup Table, or Prelookup block.
	B	Clear block parameter Remove protection against out-of-range index in generated code in each Interpolation Using Prelookup block.
Note	If the lookup table inputs are not guaranteed to fall within the range of valid breakpoint values, exclusion of range-checking code may produce unexpected results.	
Rationale	A,B	Protect against out-of-range inputs or indices.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check usage of lookup table blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check usage of lookup table blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check usage of lookup table blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check usage of lookup table blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check usage of lookup table blocks <p>For check details, see “Check usage of lookup table blocks” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, Sections MB.6.3.1.g and MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' 	
Last Changed	R2017b	

Stateflow Chart Considerations

- “Chart Properties” on page 3-2
- “Chart Architecture” on page 3-7

Chart Properties

In this section...
“hisf_0001: State Machine Type” on page 3-2
“hisf_0002: User-specified state/transition execution order” on page 3-3
“hisf_0009: Strong data typing (Simulink and Stateflow boundary)” on page 3-4
“hisf_0011: Stateflow debugging settings” on page 3-5

hisf_0001: State Machine Type

ID: Title	hisf_0001: State Machine Type
Description	To create Stateflow charts that implement consistent Stateflow semantics, use the same State Machine Type (Classic, Mealy, or Moore) for all charts in the model.
Note	<p>In Mealy charts, actions are associated with transitions. In the Moore charts, actions are associated with states. In Classic charts, actions can be associated with both transition and states.</p> <p>At compile time, Stateflow verifies that the chart semantics comply with the formal definitions and rules of the selected type of state machine. If the chart semantics are not in compliance, the software provides a diagnostic message.</p>
Rationale	Promote a clear modeling style.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check state machine type of Stateflow charts • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check state machine type of Stateflow charts • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check state machine type of Stateflow charts • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check state machine type of Stateflow charts • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check state machine type of Stateflow charts <p>For check details, see “Check state machine type of Stateflow charts” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • DO-331, Section MB.6.3.3.e 'Software architecture conform to standards'

ID: Title	hisf_0001: State Machine Type
See Also	<ul style="list-style-type: none"> • “Specify Properties for Stateflow Charts” (Stateflow) • “Create Mealy and Moore Charts” (Stateflow)
Last Changed	R2018b

hisf_0002: User-specified state/transition execution order

ID: Title	hisf_0002: User-specified state/transition execution order	
Description	Do the following to explicitly set the execution order for active states and valid transitions in Stateflow charts:	
	A	In the Chart Properties dialog box, select User specified state/transition execution order .
Prerequisites	hisl_0311: Configuration Parameters > Diagnostics > Stateflow	
Note	<p>Selecting User specified state/transition execution order restricts the dependency of a Stateflow chart semantics on the geometric position of parallel states and transitions.</p> <p>Specifying the execution order of states and transitions allows you to enforce determinism in the search order for active states and valid transitions. You have control of the order in which parallel states are executed and transitions originating from a source are tested for execution. If you do not explicitly set the execution order, the Stateflow software determines the execution order following a deterministic algorithm.</p>	
Rationale	A	Promote an unambiguous modeling style.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow charts for ordering of states and transitions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow charts for ordering of states and transitions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow charts for ordering of states and transitions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow charts for ordering of states and transitions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow charts for ordering of states and transitions <p>For check details, see “Check Stateflow charts for ordering of states and transitions” (Simulink Check).</p>	

ID: Title	hisf_0002: User-specified state/transition execution order
References	<p>This guideline supports adhering to:</p> <ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • DO-331, Section MB.6.3.3.e 'Software architecture conform to standards' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (5) 'Design and coding standards' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1e) 'Use of well-trusted design principles' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1g) 'Use of style guides' • ISO 26262-6, Table 1 (1h) 'Use of naming conventions' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.12 (1) 'Coding Standard' • EN 50128, Table A.12 (2) 'Coding Style Guide'
See Also	<ul style="list-style-type: none"> • “Specify Properties for Stateflow Charts” (Stateflow) • “Evaluate Transitions” (Stateflow) • “Execution Order for Parallel States” (Stateflow)
Last Changed	R2018b

hisf_0009: Strong data typing (Simulink and Stateflow boundary)

ID: Title	hisf_0009: Strong data typing (Simulink and Stateflow boundary)	
Description	To support strong data typing between Simulink and Stateflow ,	
	A	Select chart property Use Strong Data Typing with Simulink I/O.
Notes	By default, input to and output from Stateflow charts are of type <code>double</code> . To interface directly with Simulink signals of data types other than <code>double</code> , select Use Strong Data Typing with Simulink I/O . In this mode, data types between the Simulink and Stateflow boundary are strongly typed, and the Simulink software does not treat the data types as <code>double</code> . The Stateflow chart accepts input signals of any data type supported by the Simulink software, provided that the type of the input signal matches the type of the corresponding Stateflow input data object. Otherwise, the software reports a type mismatch error.	
Rationale	A	Support strongly typed code.

ID: Title	hisf_0009: Strong data typing (Simulink and Stateflow boundary)
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check for Strong Data Typing with Simulink I/O • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check for Strong Data Typing with Simulink I/O • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check for Strong Data Typing with Simulink I/O • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check for Strong Data Typing with Simulink I/O • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check for Strong Data Typing with Simulink I/O <p>For check details, see .</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) - Language subset • IEC 61508-3, Table A.4 (5) - Design and coding standards • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • ISO 26262-6, Table 1 (1d) - Use of defensive implementation techniques • ISO 26262-6, Table 1 (1e) - Use of well-trusted design principles • ISO 26262-6, Table 1 (1f) - Use of unambiguous graphical representation • ISO 26262-6, Table 1 (1g) - Use of style guides • ISO 26262-6, Table 1 (1h) - Use of naming conventions • EN 50128, Table A.3 (1) - Defensive Programming • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) - Language Subset
See Also	"Specify Properties for Stateflow Charts" (Stateflow)
Last Changed	R2017b

hisf_0011: Stateflow debugging settings

ID: Title	hisf_0011: Stateflow debugging settings
Description	<p>To protect against unreachable code and indeterminate execution time,</p> <p>Set configuration parameters Wrap on overflow and Simulation range checking to error.</p> <p>In the model, open the Debug tab and select Diagnostics > Detect Cyclical Behavior</p>

ID: Title	hisf_0011: Stateflow debugging settings
	Right-click on each truth table in the model and select Properties . Set these parameters to Error: <ul style="list-style-type: none"> • Underspecified • Overspecified
Notes	Run-time diagnostics are only triggered during simulation. If the error condition is not reached during simulation, the error message is not triggered for code generation.
Rationale	Protect against unreachable code and unpredictable execution time. 'B
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow debugging options • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow debugging options • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow debugging options • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow debugging options • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow debugging options For check details, see “Check Stateflow debugging options” (Simulink Check).
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) - Language subset • IEC 61508-3, Table A.4 (5) - Design and coding standards • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • ISO 26262-6, Table 1 (1d) - 'Use of defensive implementation techniques' • ISO 26262-6, Table 1 (1e) - 'Use of well-trusted design principles' • ISO 26262-6, Table 1 (1f) - 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1g) - 'Use of style guides' • ISO 26262-6, Table 1 (1h) - 'Use of naming conventions' • EN 50128, Table A.3 (1) - Defensive Programming • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) - Language Subset
See Also	“Specify Properties of Truth Table Functions” (Stateflow)
Last Changed	R2017b

Chart Architecture

In this section...
“hisf_0003: Usage of bitwise operations” on page 3-7
“hisf_0004: Usage of recursive behavior” on page 3-8
“hisf_0007: Usage of junction conditions (maintaining mutual exclusion)” on page 3-9
“hisf_0013: Usage of transition paths (crossing parallel state boundaries)” on page 3-10
“hisf_0014: Usage of transition paths (passing through states)” on page 3-12
“hisf_0015: Strong data typing (casting variables and parameters in expressions)” on page 3-13
“hisf_0016: Stateflow port names” on page 3-15
“hisf_0017: Stateflow data object scoping” on page 3-16

hisf_0003: Usage of bitwise operations

ID: Title	hisf_0003: Usage of bitwise operations	
Description	When using bitwise operations in Stateflow blocks,	
	A	Avoid signed integer data types as operands to the bitwise operations.
Notes	Normally, bitwise operations are not meaningful on signed integers. Undesired behavior can occur. For example, a shift operation might move the sign bit into the number, or a numeric bit into the sign bit.	
Rationale	A	Promote unambiguous modeling style.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check usage of bitwise operations in Stateflow charts • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check usage of bitwise operations in Stateflow charts • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check usage of bitwise operations in Stateflow charts • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check usage of bitwise operations in Stateflow charts • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check usage of bitwise operations in Stateflow charts <p>For check details, see “Check usage of bitwise operations in Stateflow charts” (Simulink Check).</p>	

ID: Title	hisf_0003: Usage of bitwise operations
References	<ul style="list-style-type: none"> IEC 61508-3, Table A.3 (3) 'Language subset' IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' IEC 62304, 5.5.3 - Software Unit acceptance criteria ISO 26262-6, Table 1 (1b) 'Use of language subsets' ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' EN 50128, Table A.4 (11) 'Language Subset' EN 50128, Table A.3 (1) 'Defensive Programming' DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' DO-331, Section 6.3.1.g 'Algorithms are accurate' DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' DO-331, Section MB.6.3.2.g 'Algorithms are accurate' MISRA C:2012, Rule 10.1
See Also	"hisf_0019: Usage of bitwise operations" on page 2-41
Last Changed	R2016a

hisf_0004: Usage of recursive behavior

ID: Title	hisf_0004: Usage of recursive behavior
Description	To support bounded function call behavior, avoid using design patterns that include unbounded recursive behavior. Recursive behavior is bound if you do the following:
	A Use an explicit termination condition that is local to the recursive call.
	B Make sure the termination condition is reached.
Notes	This rule only applies if a chart is a classic Stateflow chart. If Mealy and Moore semantics are followed, recursive behavior is prevented due to restrictions in the chart semantics. To detect the error during chart simulation, open your Stateflow chart and, in the Debug tab, select Diagnostics > Detect Cyclical Behavior .
Rationale	A, B Promote bounded function call behavior.
References	<ul style="list-style-type: none"> IEC 61508-3, Table B.1 (6) 'Limited use of recursion' IEC 62304, 5.5.3 - Software Unit acceptance criteria ISO 26262-6, Table 6 (1j) 'No recursions' EN 50128, Table A.12 (6) 'Limited Use of Recursion' DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' DO-331, Section MB.6.3.1.g 'Algorithms are accurate' DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' DO-331, Section MB.6.3.2.g 'Algorithms are accurate' MISRA C:2012, Rule 17.2
Last Changed	R2016a

ID: Title	hisf_0004: Usage of recursive behavior
Examples	<p data-bbox="305 296 1286 327">There are multiple patterns in Stateflow that can result in unbounded recursion.</p> <div data-bbox="315 359 982 611"> </div> <p data-bbox="305 653 638 684">Recursive Function Calls</p> <p data-bbox="305 695 1489 856">When the default state A is entered, event Evn is broadcast in the entry action of A. Evn results in a recursive call of the interpretation algorithm. Since A is active, the outgoing transition of A is tested. Since the current event Evn matches the transition event (and because of the absence of condition) the condition action is executed, broadcasting Evn again. This results in a new call of the interpretation algorithm which repeats the same sequence of steps until stack overflow.</p> <div data-bbox="315 894 982 1276"> </div> <p data-bbox="305 1318 638 1350">Recursive Function Calls</p>

hisf_0007: Usage of junction conditions (maintaining mutual exclusion)

ID: Title	hisf_0007: Usage of junction conditions (maintaining mutual exclusion)	
Description	To enhance clarity and prevent the generation of unreachable code:	
	A	Make junction conditions mutually exclusive.
Notes	You can use this guideline to maintain a modeling language subset in high-integrity projects.	
Rationale	A	Enhance clarity and prevent generation of unreachable code.

ID: Title	hisf_0007: Usage of junction conditions (maintaining mutual exclusion)
References	<ul style="list-style-type: none"> DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' DO-331, Section MB.6.3.1.d 'High-level requirements are verifiable' DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' DO-331, Section MB.6.3.2.d 'Low-level requirements are verifiable' DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards'
Last Changed	R2012b
Example	

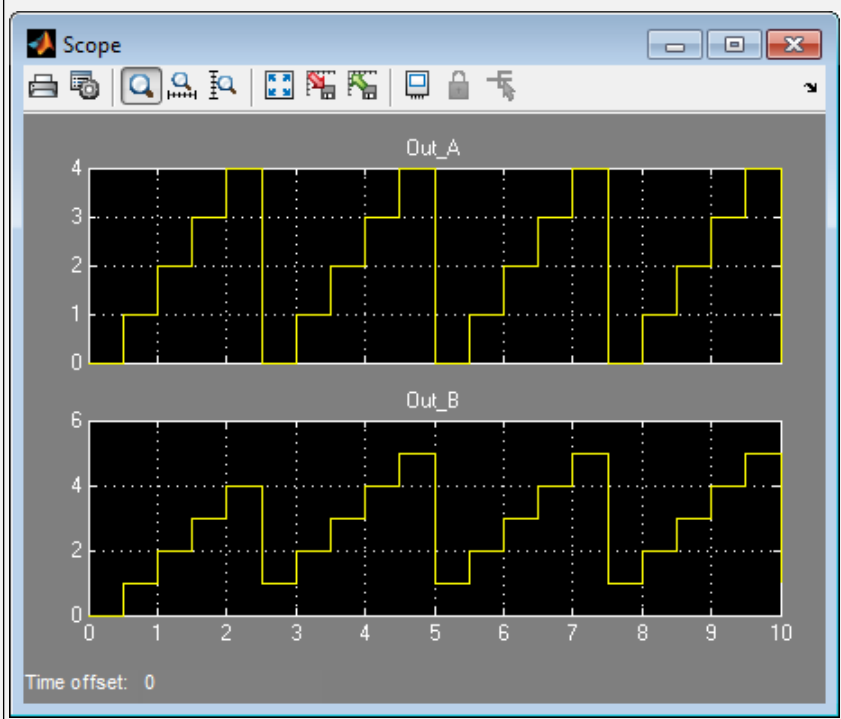
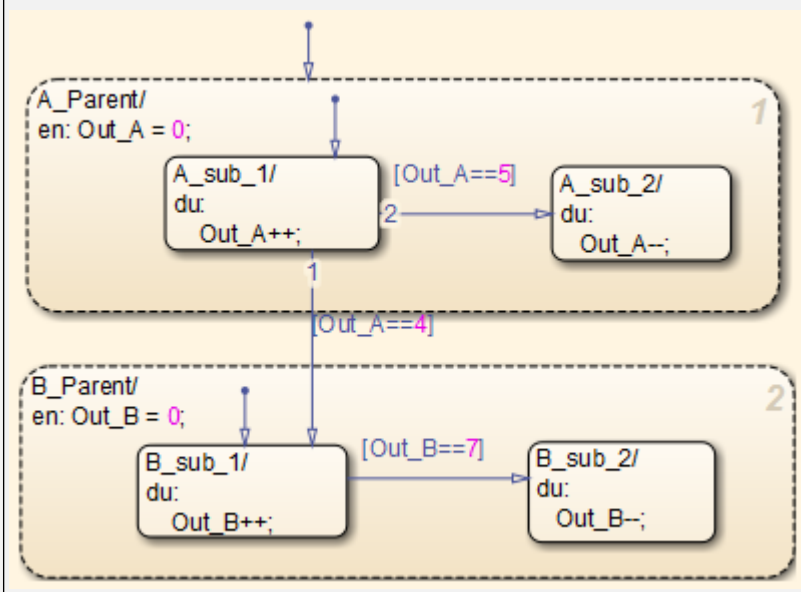
hisf_0013: Usage of transition paths (crossing parallel state boundaries)

ID: Title	hisf_0013: Usage of transition paths (crossing parallel state boundaries)
Description	To avoid creating diagrams that are hard to understand,
	A Avoid creating transitions that cross from one parallel state to another.
Notes	You can use this guideline to maintain a modeling language subset in high-integrity projects.
Rationale	A Enhance model readability.
Model Advisor Checks	<ul style="list-style-type: none"> By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow charts for transition paths that cross parallel state boundaries By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow charts for transition paths that cross parallel state boundaries By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow charts for transition paths that cross parallel state boundaries By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow charts for transition paths that cross parallel state boundaries By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow charts for transition paths that cross parallel state boundaries <p>For check details, see “Check Stateflow charts for transition paths that cross parallel state boundaries” (Simulink Check).</p>

ID: Title	hisf_0013: Usage of transition paths (crossing parallel state boundaries)
References	<ul style="list-style-type: none">• IEC 61508-3, Table A.3 (3) 'Language subset'• IEC 62304, 5.5.3 - Software Unit acceptance criteria• ISO 26262-6, Table 1 (1b) 'Use of language subsets'• EN 50128, Table A.4 (11) 'Language Subset'• DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent'• DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards'• DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent'• DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards'
Last Changed	R2017b

hisf_0013: Usage of transition paths (crossing parallel state boundaries)

Example In the following example, when Out_A is 4, both parent states (A_Parent and B_Parent) are reentered. Reentering the parent states resets the values of Out_A and Out_B to zero.



hisf_0014: Usage of transition paths (passing through states)

ID: Title hisf_0014: Usage of transition paths (passing through states)

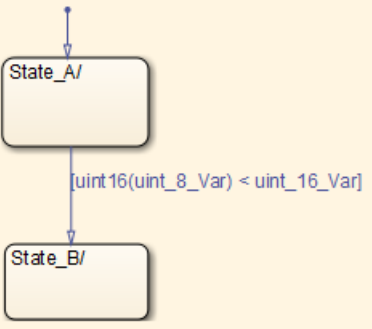
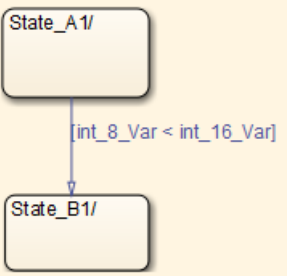
Description To avoid creating diagrams that are confusing and include transition paths without benefit,

ID: Title	hisf_0014: Usage of transition paths (passing through states)	
	A	Avoid transition paths that go into and out of a state without ending on a substate.
Notes	You can use this guideline to maintain a modeling language subset in high-integrity projects.	
Rationale	A	Enhance model readability.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check for inappropriate use of transition paths • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check for inappropriate use of transition paths • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check for inappropriate use of transition paths • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check for inappropriate use of transition paths • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check for inappropriate use of transition paths <p>For check details, see “Check for inappropriate use of transition paths” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' 	
Last Changed	R2018b	
Examples		

hisf_0015: Strong data typing (casting variables and parameters in expressions)

ID: Title	hisf_0015: Strong data typing (casting variables and parameters in expressions)	
Description	To facilitate strong data typing,	
	A	Explicitly type cast variables and parameters of different data types in: <ul style="list-style-type: none"> • Transition evaluations • Transition assignments • Assignments in states

ID: Title	hisf_0015: Strong data typing (casting variables and parameters in expressions)	
Notes	The Stateflow software automatically casts variables of different type into the same data type. This guideline helps clarify data types of the intermediate variables.	
Rationale	A	Apply strong data typing.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow charts for strong data typing • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow charts for strong data typing • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow charts for strong data typing • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow charts for strong data typing • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow charts for strong data typing <p>For check details, see “Check Stateflow charts for strong data typing” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) ‘Strongly typed programming language’ • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1c) ‘Enforcement of strong typing’ • EN 50128, Table A.4 (8) ‘Strongly Typed Programming Language’ • DO-331, Section MB.6.3.1.b ‘High-level requirements are accurate and consistent’ • DO-331, Section MB.6.3.1.e ‘High-level requirements conform to standards’ • DO-331, Section MB.6.3.1.g ‘Algorithms are accurate’ • DO-331, Section MB.6.3.2.b ‘Low-level requirements are accurate and consistent’ • DO-331, Section MB.6.3.2.e ‘Low-level requirements conform to standards’ • DO-331, Section MB.6.3.2.g ‘Algorithms are accurate’ 	
Last Changed	R2017b	

ID: Title	hisf_0015: Strong data typing (casting variables and parameters in expressions)
Examples	 <p>Recommended</p>  <p>Not Recommended</p>

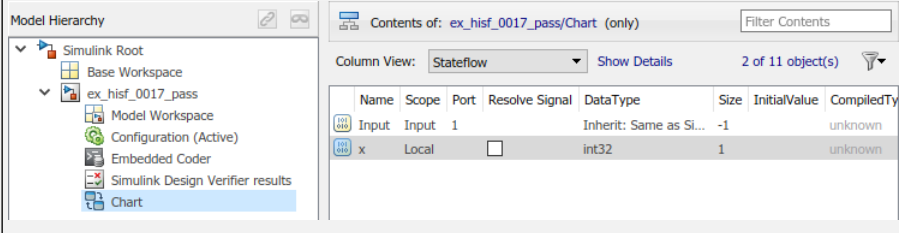
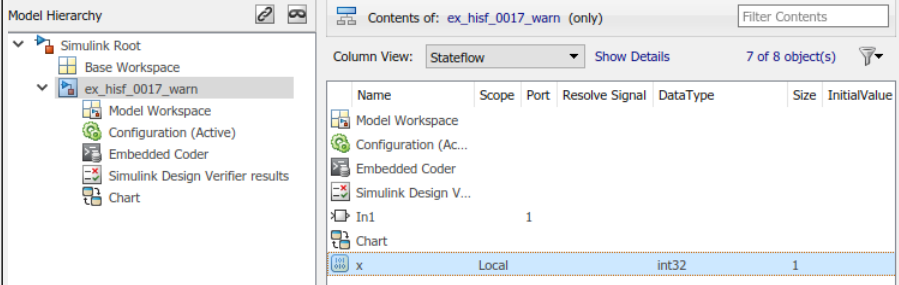
hisf_0016: Stateflow port names

ID: Title	hisf_0016: Stateflow port names
Description	The name of a Stateflow input or output must be the same as the corresponding signal. An exception to the guideline is that reusable Stateflow blocks can have different port names.
Rationale	Support generation of traceable code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check naming of ports in Stateflow charts • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check naming of ports in Stateflow charts • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check naming of ports in Stateflow charts • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check naming of ports in Stateflow charts • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check naming of ports in Stateflow charts <p>For check details, see “Check naming of ports in Stateflow charts” (Simulink Check).</p>

ID: Title	hisf_0016: Stateflow port names
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset'
Last Changed	2018a

hisf_0017: Stateflow data object scoping

ID: Title	hisf_0017: Stateflow data object scoping
Description	Stateflow data objects with local scope must be defined at the chart level or below.
Rationale	Support generation of traceable code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check scoping of Stateflow data objects • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check scoping of Stateflow data objects • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check scoping of Stateflow data objects • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check scoping of Stateflow data objects • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check scoping of Stateflow data objects <p>For check details, see “Check scoping of Stateflow data objects” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset'
Last Changed	2018a

ID: Title	hisf_0017: Stateflow data object scoping																																																								
Examples	<p>Recommended</p>  <table border="1" data-bbox="654 384 1222 468"> <thead> <tr> <th>Name</th> <th>Scope</th> <th>Port</th> <th>Resolve Signal</th> <th>Data Type</th> <th>Size</th> <th>Initial Value</th> <th>Compiled Type</th> </tr> </thead> <tbody> <tr> <td>Input</td> <td>Input</td> <td>1</td> <td></td> <td>Inherit: Same as Si...</td> <td>-1</td> <td></td> <td>unknown</td> </tr> <tr> <td>x</td> <td>Local</td> <td></td> <td><input type="checkbox"/></td> <td>int32</td> <td>1</td> <td></td> <td>unknown</td> </tr> </tbody> </table>		Name	Scope	Port	Resolve Signal	Data Type	Size	Initial Value	Compiled Type	Input	Input	1		Inherit: Same as Si...	-1		unknown	x	Local		<input type="checkbox"/>	int32	1		unknown																															
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<p>Not Recommended</p>  <table border="1" data-bbox="654 699 1222 898"> <thead> <tr> <th>Name</th> <th>Scope</th> <th>Port</th> <th>Resolve Signal</th> <th>Data Type</th> <th>Size</th> <th>Initial Value</th> </tr> </thead> <tbody> <tr> <td>Model Workspace</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Configuration (Ac...</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Embedded Coder</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Simulink Design V...</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>in1</td> <td></td> <td>1</td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>Chart</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> </tr> <tr> <td>x</td> <td>Local</td> <td></td> <td><input type="checkbox"/></td> <td>int32</td> <td>1</td> <td></td> </tr> </tbody> </table>		Name	Scope	Port	Resolve Signal	Data Type	Size	Initial Value	Model Workspace							Configuration (Ac...							Embedded Coder							Simulink Design V...							in1		1					Chart							x	Local		<input type="checkbox"/>	int32	1	
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MATLAB Function and MATLAB Code Considerations

- “MATLAB Functions” on page 4-2
- “MATLAB Code” on page 4-8
- “himl_0011: Data type and size of condition expressions” on page 4-19

MATLAB Functions

In this section...

“himl_0001: Usage of standardized MATLAB function headers” on page 4-2

“himl_0002: Strong data typing at MATLAB function boundaries” on page 4-3

“himl_0003: Limitation of MATLAB function complexity” on page 4-5

himl_0001: Usage of standardized MATLAB function headers

ID: Title	himl_0001: Usage of standardized MATLAB function headers
Description	When using MATLAB functions, use a standardized header to provide information about the purpose and use of the function.
Rationale	A standardized header improves the readability and documentation of MATLAB functions. The header should provide a function description and usage information.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check usage of standardized MATLAB function headers • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check usage of standardized MATLAB function headers • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check usage of standardized MATLAB function headers • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check usage of standardized MATLAB function headers • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check usage of standardized MATLAB function headers <p>For check details, see “Check usage of standardized MATLAB function headers” (Simulink Check).</p>
References	DO-331, Section MB.6.3.4.e - Source code is traceable to low-level requirements
See Also	<ul style="list-style-type: none"> • MathWorks Advisory Board (MAB) guideline na_0025: MATLAB Function header • Orion GN&C: MATLAB and Simulink Standards, jh_0073: eML Header • “MATLAB Function Block Editor”
Last Changed	R2018b

ID: Title	himl_0001: Usage of standardized MATLAB function headers
Examples	<p>A typical standardized function header includes:</p> <ul style="list-style-type: none"> • Function name • Description • Inputs and outputs (if possible, include size and type) • Assumptions and limitations • Revision history <p>Example:</p> <pre>% FUNCTION NAME: % avg % % DESCRIPTION: % Compute the average of three inputs % % INPUT: % in1 - (double) Input one % in2 - (double) Input two % in3 - (double) Input three % % OUTPUT: % out - (double) Calculated average of the three inputs % % ASSUMPTIONS AND LIMITATIONS: % None % % REVISION HISTORY: % 05/02/2018 - mmyers % * Initial implementation %</pre>

himl_0002: Strong data typing at MATLAB function boundaries

ID: Title	himl_0002: Strong data typing at MATLAB function boundaries
Description	<p>To support strong data typing at the interfaces of MATLAB functions, explicitly define the interface for input signals, output signals, and parameters, by setting:</p> <ul style="list-style-type: none"> • Complexity • Type
Rationale	<p>Defined interfaces:</p> <ul style="list-style-type: none"> • Allow consistency checking of interfaces. • Prevent unintended generation of different functions for different input and output types. • Simplify testing of functions by limiting the number of test cases.

ID: Title	himl_0002: Strong data typing at MATLAB function boundaries
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check for MATLAB Function interfaces with inherited properties • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check for MATLAB Function interfaces with inherited properties • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check for MATLAB Function interfaces with inherited properties • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check for MATLAB Function interfaces with inherited properties • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check for MATLAB Function interfaces with inherited properties <p>For check details, see “Check for MATLAB Function interfaces with inherited properties” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table B.9 (6) - Fully defined interface • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1c) - Enforcement of strong typing • ISO 26262-6, Table 1 (1f) - Use of unambiguous graphical representation • EN 50128, Table A.1 (11) - Software Interface Specifications • DO-331, Section MB.6.3.2.b - Low-level requirements are accurate and consistent
See Also	<ul style="list-style-type: none"> • MathWorks Advisory Board (MAB) guideline na_0034: MATLAB Function block input/output settings • Orion GN&C: MATLAB and Simulink Standards, jh_0063: eML block input / output settings • “MATLAB Function Block Editor”
Last Changed	R2016a

ID: Title	himl_0002: Strong data typing at MATLAB function boundaries
Examples	<p>Recommended:</p> <p>In the “Ports and Data Manager”, specify the complexity and type of input u1 as follows:</p> <ul style="list-style-type: none"> • Complexity to Off • Type to uint16 <div data-bbox="391 512 1195 816" style="text-align: center;"> </div> <p>Not Recommended:</p> <p>In the “Ports and Data Manager”, do <i>not</i> specify the complexity and type of input u1 as follows:</p> <ul style="list-style-type: none"> • Complexity to Inherited • Type to Inherit: Same as Simulink. <p>Note To access the “Ports and Data Manager”, from the toolbar of the “MATLAB Function Block Editor”, select Edit Data.</p>

himl_0003: Limitation of MATLAB function complexity

ID: Title	himl_0003: Limitation of MATLAB function complexity
Description	<p>When using MATLAB functions, limit the size and complexity of MATLAB code. The size and complexity of MATLAB functions is characterized by:</p> <ul style="list-style-type: none"> • Lines of code • Nested function levels • Cyclomatic complexity • Density of comments (ratio of comment lines to lines of code)

ID: Title	himl_0003: Limitation of MATLAB function complexity	
Note	Size and complexity limits can vary across projects. Typical limits might be as described in this table:	
	Metric	Limit
	Lines of code	60 per MATLAB function
	Nested function levels	3 ^{1,2}
	Cyclomatic complexity	15
	Density of comments	0.2 comment lines per line of code
	¹ Pure Wrappers to external functions are not counted as separate levels. ² Standard MATLAB library functions do not count as separate levels.	
Rationale	<ul style="list-style-type: none"> • Readability • Comprehension • Traceability • Maintainability • Testability 	
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check MATLAB Function metrics • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check MATLAB Function metrics • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check MATLAB Function metrics • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check MATLAB Function metrics • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check MATLAB Function metrics <p>For check details, see “Check MATLAB Function metrics” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • IEC 61508-3, Table B.9 (6) - Fully defined interface • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1a) - Enforcement of low complexity • ISO 26262-6, Table 1 (1f) - Use of unambiguous graphical representation • EN 50128, Table A.1(11) - Software Interface Specifications • DO-331, Sections MB.6.3.1.e - High-level requirements conform to standards • DO-331, Sections MB.6.3.2.e - Low-level requirements conform to standards 	

ID: Title	himl_0003: Limitation of MATLAB function complexity
See Also	<ul style="list-style-type: none">• MathWorks Advisory Board (MAB) guideline na_0016: Source lines of MATLAB Functions• MathWorks Automotive Advisory Board (MAAB) guideline na_0017: Number of called function levels• MathWorks Automotive Advisory Board (MAAB) guideline na_0018: Number of nested if/else and case statement• Orion GN&C: MATLAB and Simulink Standards, jh_0084: eML Comments• "MATLAB Function Block Editor"
Last Changed	R2016a

MATLAB Code

In this section...
“himl_0004: MATLAB Code Analyzer recommendations for code generation” on page 4-8
“himl_0006: MATLAB code if / elseif / else patterns” on page 4-10
“himl_0007: MATLAB code switch / case / otherwise patterns” on page 4-12
“himl_0008: MATLAB code relational operator data types” on page 4-14
“himl_0009: MATLAB code with equal / not equal relational operators” on page 4-16
“himl_0010: MATLAB code with logical operators and functions” on page 4-17

himl_0004: MATLAB Code Analyzer recommendations for code generation

ID: Title	himl_0004: MATLAB Code Analyzer recommendations for code generation	
Description	When using MATLAB code:	
	A	To activate MATLAB Code Analyzer messages for code generations, use the <code> %#codegen</code> directive in external MATLAB functions.
	B	Review the MATLAB Code Analyzer messages. Either: <ul style="list-style-type: none"> • Implement the recommendations or • Justify not following the recommendations with <code> %#ok<message-ID(S)></code> directives in the MATLAB function. Do not use <code> %#ok</code> without specific message-IDs.
Notes	The MATLAB Code Analyzer messages provide identifies potential errors, problems, and opportunities for improvement in the code.	
Rationale	A	In external MATLAB functions, the <code> %#codegen</code> directive activates MATLAB Code Analyzer messages for code generation.
	B	<ul style="list-style-type: none"> • Following MATLAB Code Analyzer recommendations helps to: <ul style="list-style-type: none"> • Generate efficient code. • Follow best code generation practices • Avoid using MATLAB features not supported for code generation. • Avoid code patterns which potentially influence safety. • Not following MATLAB Code Analyzer recommendations are justified with message id (e.g. <code> %#ok<NOPRT></code>). <p>In the MATLAB function, using <code> %#ok</code> without a message id justifies the full line, potentially hiding issues.</p>

ID: Title	himl_0004: MATLAB Code Analyzer recommendations for code generation
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check MATLAB Code Analyzer messages • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check MATLAB Code Analyzer messages • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check MATLAB Code Analyzer messages • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check MATLAB Code Analyzer messages • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check MATLAB Code Analyzer messages <p>For check details, see “Check MATLAB Code Analyzer messages” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 61508-3, Table A.4 (5) 'Design and coding standards' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • ISO 26262-6, Table 1 (1e) 'Use of well-trusted design principles' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1g) 'Use of style guides' • ISO 26262-6, Table 1 (1h) 'Use of naming conventions' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • EN 50128, Table A.12 (1) 'Coding Standard' • EN 50128, Table A.12 (2) 'Coding Style Guide' • DO-331, Section MB.6.3.1.b 'Accuracy and consistency' • DO-331, Section MB.6.3.2.b 'Accuracy and consistency'
See Also	“Check Code for Errors and Warnings” (MATLAB)
Last Changed	R2016a

ID: Title	himl_0004: MATLAB Code Analyzer recommendations for code generation
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • Activate MATLAB Code Analyzer messages for code generations: <pre> %#codegen function y = function(u) y = inc_u(u); end function yy = inc_u(uu) yy = uu + 1; end </pre> • Justify missing ; and value assigned might be unused: <pre> y = 2*u %#ok<NOPRT,NAGSU> output for debugging ... y = 3*u; </pre> • If output is not desired and assigned value is unused, remove the line <code>y = 2*u ...</code>: <pre> y = 3*u; </pre> <p>Not Recommended</p> <ul style="list-style-type: none"> • External MATLAB file used in Simulink with missing <code>%#codegen</code> directive: <pre> function y = function(u) % nested functions can't be used for code generation function yy = inc_u(uu) yy = uu + 1; end y = inc_u(u); end </pre> • All messages in line are justified by using <code>%#ok</code> without a message ID: <pre> % missing ';' and the value might be unused y = 2*u %#ok ... y = 3*u; </pre> • No justification: <pre> % missing justification for missing ';' and unnecessary '['..' y= [2*u] </pre>

himl_0006: MATLAB code if / elseif / else patterns

ID: Title	himl_0006: MATLAB code if / elseif / else patterns
Description	For MATLAB code with <code>if / elseif / else</code> constructs, terminate the constructs with an <code>else</code> statement that includes at least a meaningful comment. A final <code>else</code> statement is not required if there is no <code>elseif</code> .

ID: Title	himl_0006: MATLAB code if / elseif / else patterns
Rationale	<ul style="list-style-type: none"> • Defensive programming • Readability • Traceability
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check if/elseif/else patterns in MATLAB Function blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check if/elseif/else patterns in MATLAB Function blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check if/elseif/else patterns in MATLAB Function blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check if/elseif/else patterns in MATLAB Function blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check if/elseif/else patterns in MATLAB Function blocks <p>For check details, see “Check if/elseif/else patterns in MATLAB Function blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.1.e 'Conformance to standards' • DO-331, Section MB.6.3.2.e 'Conformance to standards' • DO-331, Section MB.6.3.3.e 'Conformance to standards'
See Also	<ul style="list-style-type: none"> • “himl_0010: Usage of If blocks and If Action Subsystem blocks” on page 2-19
Last Changed	R2018b

ID: Title	himl_0006: MATLAB code if / elseif / else patterns
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • <pre>if u > 0 y = 1; end</pre> • <pre>if u > 0 y = 1; elseif u < 0 y = -1; else y = 0; end</pre> • <pre>y = 0; if u > 0 y = 1; elseif u < 0 y = -1; else % handled before if end</pre> <p>Not Recommended</p> <ul style="list-style-type: none"> • <pre>% empty else y = 0; if u > 0 y = 1; elseif u < 0 y = -1; else end</pre> • <pre>% missing else y = 0; if u > 0 y = 1; elseif u < 0 y = -1; end</pre>

himl_0007: MATLAB code switch / case / otherwise patterns

ID: Title	himl_0007: MATLAB code switch / case / otherwise patterns
Description	<p>For MATLAB code with switch statements, include:</p> <ul style="list-style-type: none"> • At least two case statements. • An otherwise statement that at least includes a meaningful comment.
Note	<p>If there is only one case and one otherwise statement, consider using an if / else statement.</p>

ID: Title	himl_0007: MATLAB code switch / case / otherwise patterns
Rationale	<ul style="list-style-type: none"> • Defensive programming • Readability • Traceability
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check switch statements in MATLAB Function blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check switch statements in MATLAB Function blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check switch statements in MATLAB Function blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check switch statements in MATLAB Function blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check switch statements in MATLAB Function blocks <p>For check details, see “Check switch statements in MATLAB Function blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • DO-331, Section MB.6.3.1.e 'Conformance to standards' • DO-331, Section MB.6.3.2.e 'Conformance to standards' • DO-331, Section MB.6.3.3.e 'Conformance to standards' • MISRA C:2012, Rule 16.4
See Also	<ul style="list-style-type: none"> • na_0022: Recommended patterns for Switch/Case statements • “hisl_0011: Usage of Switch Case blocks and Action Subsystem blocks” on page 2-21
Last Changed	R2018b

ID: Title	himl_0007: MATLAB code switch / case / otherwise patterns
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • <pre>switch u case 1 y = 3; case 3 y = 1; otherwise y = 1; end</pre> • <pre>y = 0; switch u case 1 y = 3; case 3 y = 1; otherwise % handled before switch end</pre> <p>Not Recommended</p> <ul style="list-style-type: none"> • <pre>% no case statements switch u otherwise y = 1; end</pre> • <pre>% empty otherwise statement switch u case 1 y = 3; case 3 y = 1; otherwise end</pre> • <pre>% no otherwise statement switch u case 1 y = 3; end</pre>

himl_0008: MATLAB code relational operator data types

ID: Title	himl_0008: MATLAB code relational operator data types
Description	For MATLAB code with relational operators, use the same data type for the left and right operands.
Note	If the two operands have different data types, MATLAB will promote both operands to a common data type. This can lead to unexpected results.
Rationale	<ul style="list-style-type: none"> • Prevent implicit casts • Prevent unexpected results

ID: Title	himl_0008: MATLAB code relational operator data types
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check usage of relational operators in MATLAB Function blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check usage of relational operators in MATLAB Function blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check usage of relational operators in MATLAB Function blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check usage of relational operators in MATLAB Function blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check usage of relational operators in MATLAB Function blocks <p>For check details, see “Check usage of relational operators in MATLAB Function blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(c) 'Enforcement of strong typing' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) 'Language Subset'
See Also	<ul style="list-style-type: none"> • “himl_0016: Usage of blocks that compute relational operators” on page 2-38 • “himl_0017: Usage of blocks that compute relational operators (2)” on page 2-39
Last Changed	R2018b
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • <code>myBool == true</code> <code>myInt8 == int8(1)</code> <p>Not Recommended</p> <ul style="list-style-type: none"> • <code>myBool == 1</code> <code>myInt8 == true</code> <code>myInt8 == 1</code> <code>myInt8 == int16(1)</code> <code>myEnum1.EnumVal == int32(1)</code>

himl_0009: MATLAB code with equal / not equal relational operators

ID: Title	himl_0009: MATLAB code with equal / not equal relational operators
Description	<p>For MATLAB code with equal or not equal relational operators, avoid using the following data types:</p> <ul style="list-style-type: none"> • Single • Double • Types derived from single or double data types
Note	<p>Consider the following code fragments:</p> <pre>1 sqrt(2)^2 == 2 2 sqrt(2^2) == 2</pre> <p>Mathematically, both fragments are true. However, because of floating point rounding effects, the results are:</p> <pre>1 false 2 true</pre>
Rationale	<ul style="list-style-type: none"> • Prevent unexpected results
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check usage of equality operators in MATLAB Function blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check usage of equality operators in MATLAB Function blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check usage of equality operators in MATLAB Function blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check usage of equality operators in MATLAB Function blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check usage of equality operators in MATLAB Function blocks <p>For check details, see “Check usage of equality operators in MATLAB Function blocks” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • EN 50128, MB.6.3.2.g 'Defensive Programming' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Dir 1.1

ID: Title	himl_0009: MATLAB code with equal / not equal relational operators
See Also	<ul style="list-style-type: none"> • jc_0481: Use of hard equality comparisons for floating point numbers in Stateflow • "hisl_0016: Usage of blocks that compute relational operators" on page 2-38
Last Changed	R2018b
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • <code>myDouble >= 0.99 && myDouble <= 1.01; % test range</code> <p>Not Recommended</p> <ul style="list-style-type: none"> • <code>myDouble == 1.0</code> <code>mySingle ~= 15.0</code>

himl_0010: MATLAB code with logical operators and functions

ID: Title	himl_0010: MATLAB code with logical operators and functions
Description	For logical operators and logical functions in MATLAB code, use logical data types
Notes	<p>Logical operators: <code>&&</code>, <code> </code>, <code>~</code></p> <p>Logical functions: <code>and</code>, <code>or</code>, <code>not</code>, <code>xor</code></p>
Rationale	<ul style="list-style-type: none"> • Prevent unexpected results
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check usage of logical operators and functions in MATLAB Function blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check usage of logical operators and functions in MATLAB Function blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check usage of logical operators and functions in MATLAB Function blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check usage of logical operators and functions in MATLAB Function blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check usage of logical operators and functions in MATLAB Function blocks <p>For check details, see "Check usage of logical operators and functions in MATLAB Function blocks" (Simulink Check).</p>

ID: Title	himl_0010: MATLAB code with logical operators and functions
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(c) 'Enforcement of strong typing' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) 'Language Subset' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate'
Last Changed	R2018b
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • <code>~myLogical</code> • <code>(myInt8 > int8(4)) && myLogical</code> • <code>xor(myLogical1,myLogical2)</code> <p>Not Recommended</p> <ul style="list-style-type: none"> • <code>~myInt8</code> • <code>myInt8 && myDouble</code>

himl_0011: Data type and size of condition expressions

ID: Title	himl_0011: Data type and size of condition expressions
Description	<p>Logical scalars should be used for condition expressions. Condition expressions include:</p> <ul style="list-style-type: none"> • if expressions • elseif expressions • while expressions • Condition expressions of Stateflow transitions
Rationale	Prevent execution of unexpected code paths
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > MATLAB > Check type and size of condition expressions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > MATLAB > Check type and size of condition expressions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > MATLAB > Check type and size of condition expressions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > MATLAB > Check type and size of condition expressions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > MATLAB > Check type and size of condition expressions <p>For check details, see "Check type and size of condition expressions" (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(c) 'Enforcement of strong typing' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) 'Language Subset' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012 Rule 14.4 - The controlling expression of an if statement and the controlling expression of an iteration-statement shall have essential Boolean type.
Last Changed	R2019b

ID: Title	himl_0011: Data type and size of condition expressions
Examples	<p>Recommended</p> <p>Assume variable var is a scalar of type double with value -1.</p> <p>MATLAB Code:</p> <pre>if var > 0 % expression is a logical scalar ... % will not be executed elseif var < 0 % expression is a logical scalar ... % will be executed else ... % will not be executed end while var < 5 % expression is a logical scalar var = var + 1; % executed 5 times end</pre> <p>Stateflow Transition Condition:</p> <pre>[var > 0]{...} % condition action will not be executed</pre> <p>Not Recommended</p> <p>Assume variable var is a scalar of type double with value -1.</p> <p>MATLAB Code:</p> <pre>if var % expression is a double scalar ... % will be executed because var is non-zero elseif ~var ... % will not be executed else ... % will not be executed end while var % expression is a double scalar var = var + 1; % executed 1 time end</pre> <p>Stateflow Transition Condition:</p> <pre>[var]{...} % condition action will be executed because var is non-zero</pre>

Configuration Parameter Considerations

- “Solver” on page 5-2
- “Math and Data Types” on page 5-5
- “Diagnostics” on page 5-7
- “Model Referencing” on page 5-24
- “Simulation Target” on page 5-25
- “Code Generation” on page 5-26

Solver

In this section...
“hisl_0040: Configuration Parameters > Solver > Simulation time” on page 5-2
“hisl_0041: Configuration Parameters > Solver > Solver options” on page 5-3
“hisl_0042: Configuration Parameters > Solver > Tasking and sample time options” on page 5-4

hisl_0040: Configuration Parameters > Solver > Simulation time

ID: Title	hisl_0040: Configuration Parameters > Solver > Simulation time	
Description	Set these simulation time configuration parameters as follows:	
	A	Start time to 0.0.
	B	Stop time to a positive value that is less than the value of Application lifespan (days) .
Note	<p>Simulink allows nonzero start times for simulation. However, production code generation requires a zero start time.</p> <p>Stop time in seconds and Application lifespan (days) is in days.</p> <p>When configuration parameter Application lifespan (days) is set to auto (default), any positive value for Stop time is valid.</p>	
Rationale	A	Generate code that is valid for production code generation.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related solver settings for simulation time • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related solver settings for simulation time • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related solver settings for simulation time • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related solver settings for simulation time • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related solver settings for simulation time <p>For check details, see “Check safety-related solver settings for simulation time” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.g—Algorithms are accurate • DO-331 Section MB.6.3.2.g—Algorithms are accurate • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' 	

ID: Title	hisl_0040: Configuration Parameters > Solver > Simulation time
See Also	<ul style="list-style-type: none"> • “hisl_0048: Configuration Parameters > Math and Data Types > Application lifespan (days)” on page 5-6 • “Solver Pane” in the Simulink documentation
Last Changed	R2017b

hisl_0041: Configuration Parameters > Solver > Solver options

ID: Title	hisl_0041: Configuration Parameters > Solver > Solver options	
Description	For models used to develop high-integrity systems, in the Configuration Parameters dialog box, on the Solver pane, set parameters for solvers as follows:	
	A	Type to Fixed-step.
	B	Solver to discrete (no continuous states).
Note	Generating code for production requires a fixed-step, discrete solver.	
Rationale	A, B	Generate code that is valid for production code generation.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related solver settings for solver options • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related solver settings for solver options • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related solver settings for solver options • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related solver settings for solver options • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related solver settings for solver options <p>For check details, see “Check safety-related solver settings for solver options” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.g—Algorithms are accurate • DO-331 Section MB.6.3.2.g—Algorithms are accurate • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' 	
See Also	“Solver Pane” in the Simulink documentation	
Last Changed	R2017b	

hisl_0042: Configuration Parameters > Solver > Tasking and sample time options

ID: Title	hisl_0042: Configuration Parameters > Solver > Tasking and sample time options
Description	Clear configuration parameter Automatically handle rate transition for data transfer .
Notes	<p>Selecting the Automatically handle rate transition for data transfer check box can result in inserting rate transition code without a corresponding model construct. This can impede establishing full traceability or showing that unintended functions are not introduced.</p> <p>You can either select or clear the Higher priority value indicates higher task priority check box . Selecting this check box determines whether the priority for Sample time properties uses the lowest values as highest priority, or the highest values as highest priority.</p>
Rationale	Support fully specified models and unambiguous code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related solver settings for tasking and sample-time • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related solver settings for tasking and sample-time • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related solver settings for tasking and sample-time • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related solver settings for tasking and sample-time • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related solver settings for tasking and sample-time <p>For check details, see “Check safety-related solver settings for tasking and sample-time” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.4.e 'Source code is traceable to low-level requirements' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset'
See Also	“Solver Pane” in the Simulink documentation
Last Changed	R2018a

Math and Data Types

hisl_0045: Configuration Parameters > Math and Data Types > Implement logic signals as Boolean data (vs. double)

ID: Title	hisl_0045: Configuration Parameters > Math and Data Types > Implement logic signals as Boolean data (vs. double)
Description	To support unambiguous behavior when using logical operators, relational operators, and the Combinatorial Logic block, select configuration parameter Implement logic signals as Boolean data (vs. double) .
Notes	Selecting Implement logic signals as Boolean data (vs. double) enables Boolean type checking, which produces an error when blocks that prefer Boolean inputs connect to double signals. This checking results in generating code that requires less memory.
Rationale	Avoid ambiguous model behavior and optimize memory for generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for logic signals • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for logic signals • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for logic signals • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for logic signals • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for logic signals <p>For check details, see “Check safety-related optimization settings for logic signals” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, MB.6.3.2.e 'Low-level requirements conform to standards' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • MISRA C:2012, Rule 10.1
See Also	Implement logic signals as Boolean data (vs. double) in the Simulink documentation.
Last Changed	R2018b

hisl_0048: Configuration Parameters > Math and Data Types > Application lifespan (days)

ID: Title	hisl_0048: Configuration Parameters > Math and Data Types > Application lifespan (days)
Description	To support the robustness of systems that run continuously, set configuration parameter Application lifespan (days) to <code>inf</code> .
Notes	Embedded applications might run continuously. Do not assume a limited lifespan for timers and counters. When you set Application lifespan (days) to <code>inf</code> , the simulation time is less than the application lifespan.
Rationale	Support robustness of systems that run continuously.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for application lifespan • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for application lifespan • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for application lifespan • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for application lifespan • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for application lifespan <p>For check details, see “Check safety-related optimization settings for application lifespan” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming'
See Also	<ul style="list-style-type: none"> • “Application lifespan (days)” in the Simulink documentation • “hisl_0040: Configuration Parameters > Solver > Simulation time” on page 5-2
Last Changed	R2018b

Diagnostics

In this section...
"hisl_0036: Configuration Parameters > Diagnostics > Saving" on page 5-7
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"hisl_0301: Configuration Parameters > Diagnostics > Compatibility" on page 5-11
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"hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals" on page 5-22

hisl_0036: Configuration Parameters > Diagnostics > Saving

ID: Title	hisl_0036: Configuration Parameters > Diagnostics > Saving
Description	<p>Set these configuration parameters to error:</p> <ul style="list-style-type: none"> • Block diagram contains disabled library links • Block diagram contains parameterized library links
Rationale	Prevent unexpected results.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for saving • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for saving • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for saving • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for saving • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for saving <p>For check details, see "Check safety-related diagnostic settings for saving" (Simulink Check).</p>

ID: Title	hisl_0036: Configuration Parameters > Diagnostics > Saving
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • EN 50128, Table A.4 (11) 'Language Subset'
Last Changed	R2017b

hisl_0043: Configuration Parameters > Diagnostics > Solver

ID: Title	hisl_0043: Configuration Parameters > Diagnostics > Solver													
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics pane, set the Solver parameters as follows:</p> <ul style="list-style-type: none"> • Algebraic loop to error. • Minimize algebraic loop to error. • Block priority violation to error if you are using block priorities. • Automatic solver parameter selection to error. • State name clash to warning. 													
Note	<p>Enabling diagnostics pertaining to the solver provides information to detect violations of other guidelines.</p> <p>This table clarifies the result of not specifying the configuration parameter as indicated above.</p> <table border="1"> <thead> <tr> <th>Configuration Parameter</th> <th>Result</th> </tr> </thead> <tbody> <tr> <td>Algebraic loop</td> <td>Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.</td> </tr> <tr> <td>Minimize algebraic loop</td> <td>Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.</td> </tr> <tr> <td>Block priority violation</td> <td>Block execution order can include undetected conflicts that might result in unpredictable block order execution.</td> </tr> <tr> <td>Automatic solver parameter selection</td> <td>An automatic change to the solver, step size, or simulation stop time can go undetected and might the operation of generated code.</td> </tr> <tr> <td>State name clash</td> <td>A name being used for more than one state might go undetected.</td> </tr> </tbody> </table>		Configuration Parameter	Result	Algebraic loop	Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.	Minimize algebraic loop	Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.	Block priority violation	Block execution order can include undetected conflicts that might result in unpredictable block order execution.	Automatic solver parameter selection	An automatic change to the solver, step size, or simulation stop time can go undetected and might the operation of generated code.	State name clash	A name being used for more than one state might go undetected.
Configuration Parameter	Result													
Algebraic loop	Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.													
Minimize algebraic loop	Automatic breakage of algebraic loops can go undetected and might result in unpredictable block order execution.													
Block priority violation	Block execution order can include undetected conflicts that might result in unpredictable block order execution.													
Automatic solver parameter selection	An automatic change to the solver, step size, or simulation stop time can go undetected and might the operation of generated code.													
State name clash	A name being used for more than one state might go undetected.													
Rationale	Support generation of robust and unambiguous code.													

ID: Title	hisl_0043: Configuration Parameters > Diagnostics > Solver
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for solvers • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for solvers • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for solvers • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for solvers • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for solvers <p>For check details, see “Check safety-related diagnostic settings for solvers” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b - Software architecture is consistent. DO-331, MB.6.3.3.e 'Software architecture conforms to standards' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset'
See Also	<ul style="list-style-type: none"> • “Model Configuration Parameters: Diagnostics” in the Simulink documentation • jc_0021: Model diagnostic settings in the Simulink documentation
Last Changed	R2018b

hisl_0044: Configuration Parameters > Diagnostics > Sample Time

ID: Title	hisl_0044: Configuration Parameters > Diagnostics > Sample Time
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Sample Time pane, set these parameters to error:</p> <ul style="list-style-type: none"> • Source block specifies -1 sample time • Multitask rate transition • Single task rate transition • Multitask conditionally executed subsystem • Tasks with equal priority • Enforce sample times specified by Signal Specification blocks • Unspecified inheritability of sample times <p>If the target system does not allow preemption between tasks that have equal priority, set Tasks with equal priority to none.</p>

ID: Title	hisl_0044: Configuration Parameters > Diagnostics > Sample Time	
Note	Enabling diagnostics pertaining to the solver provides information to detect violations of other guidelines.	
	This table clarifies the result of not specifying the configuration parameter as indicated above.	
	Configuration Parameter	Result
	Source block specifies -1 sample time	Use of inherited sample times for a source block, such as Sine Wave, can go undetected and result in unpredictable execution rates for source and downstream blocks.
	Multitask rate transition	Invalid rate transitions between two blocks operating in multitasking mode can go undetected. You cannot use invalid rate transitions for embedded real-time software applications.
	Single task rate transition	A rate transition between two blocks operating in single-tasking mode can go undetected. You cannot use single-tasking rate transitions for embedded real-time software applications.
	Multitask conditionally executed subsystems	A conditionally executed multirate subsystem, operating in multitasking mode, might go undetected and corrupt data or show unexpected behavior in a target system that allows preemption.
	Tasks with equal priority	Two asynchronous tasks with equal priority might go undetected and show unexpected behavior in target systems that allow preemption.
Enforce sample times specified by Signal Specification blocks	Inconsistent sample times for a Signal Specification block and the connected destination block might go undetected and result in unpredictable execution rates.	
Unspecified inheritability of sample times	An S-function that is not explicitly set to inherit sample time can go undetected and result in unpredictable behavior.	
Rationale	A	Support generation of robust and unambiguous code.

ID: Title	hisl_0044: Configuration Parameters > Diagnostics > Sample Time
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for sample time • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for sample time • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for sample time • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for sample time • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for sample time <p>For check details, see “Check safety-related diagnostic settings for sample time” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • DO-331, Section MB.6.3.3.e - Software architecture conforms to standards. • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • EN 50128, Table A.4 (11) 'Language Subset'
See Also	“Model Configuration Parameters: Sample Time Diagnostics” in the Simulink documentation
Last Changed	R2017b

hisl_0301: Configuration Parameters > Diagnostics > Compatibility

ID: Title	hisl_0301: Configuration Parameters > Diagnostics > Compatibility
Description	Set configuration parameter S-function upgrades needed to error.
Rationale	Improve robustness of design.

ID: Title	hisl_0301: Configuration Parameters > Diagnostics > Compatibility
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for compatibility • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for compatibility • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for compatibility • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for compatibility • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for compatibility <p>For check details, see “Check safety-related diagnostic settings for compatibility” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b - Software architecture is consistent • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming'
See Also	“Model Configuration Parameters: Compatibility Diagnostics” in the Simulink documentation
Last Changed	R2017b

hisl_0302: Configuration Parameters > Diagnostics > Data Validity > Parameters

ID: Title	hisl_0302: Configuration Parameters > Diagnostics > Data Validity > Parameters
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Data Validity pane, set the Parameters parameters as follows:</p> <ul style="list-style-type: none"> • Detect downcast to error • Detect underflow to error • Detect loss of tunability to error • Detect overflow to error • Detect precision loss to error
Rationale	Improve robustness of design.

ID: Title	hisl_0302: Configuration Parameters > Diagnostics > Data Validity > Parameters
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for parameters • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for parameters • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for parameters • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for parameters • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for parameters <p>For check details, see “Check safety-related diagnostic settings for parameters” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g - Algorithms are accurate • DO-331, Section MB.6.3.2.g - Algorithms are accurate. • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming'
See Also	“Model Configuration Parameters: Data Validity Diagnostics” in the Simulink documentation
Last Changed	R2018b

hisl_0303: Configuration Parameters > Diagnostics > Data Validity > Merge blocks

ID: Title	hisl_0303: Configuration Parameters > Diagnostics > Data Validity > Merge blocks
Description	Set configuration parameter Detect multiple driving blocks executing at the same time step to error.
Rationale	Improve robustness of design.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Merge blocks • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Merge blocks • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Merge blocks • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Merge blocks • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Merge blocks <p>For check details, see “Check safety-related diagnostic settings for Merge blocks” (Simulink Check).</p>

ID: Title	hisl_0303: Configuration Parameters > Diagnostics > Data Validity > Merge blocks
References	<ul style="list-style-type: none"> • DO-331 MB.6.3.2 (b) Accuracy and Consistency • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset
See Also	“Detect multiple driving blocks executing at the same time step” in the Simulink documentation
Last Changed	R2017b

hisl_0304: Configuration Parameters > Diagnostics > Data Validity > Model initialization

ID: Title	hisl_0304: Configuration Parameters > Diagnostics > Data Validity > Model initialization
Description	Set configuration parameter Underspecified initialization to Simplified.
Rationale	Improve robustness of design.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model initialization • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model initialization • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model initialization • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model initialization • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model initialization <p>For check details, see “Check safety-related diagnostic settings for model initialization” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b - Software architecture is consistent • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset • MISRA C:2012, Rule 9.1
See Also	“Underspecified initialization detection” in the Simulink documentation
Last Changed	R2017b

hisl_0305: Configuration Parameters > Diagnostics > Data Validity > Debugging

ID: Title	hisl_0305: Configuration Parameters > Diagnostics > Data Validity > Debugging
Description	Set configuration parameter Model Verification block enabling to Disable all.
Rationale	Improve robustness of design.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data used for debugging • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data used for debugging • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data used for debugging • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data used for debugging • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for data used for debugging <p>For check details, see “Check safety-related diagnostic settings for data used for debugging” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.e - High-level requirements conform to standards • DO-331, Section MB.6.3.2.e - Low-level requirements conform to standards • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset
See Also	“Model Verification block enabling” in the Simulink documentation
Last Changed	R2017b

hisl_0306: Configuration Parameters > Diagnostics > Connectivity > Signals

ID: Title	hisl_0306: Configuration Parameters > Diagnostics > Connectivity > Signals
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Connectivity pane, set the Signals parameters as follows:</p> <ul style="list-style-type: none"> • Signal label mismatch to error • Unconnected block input ports to error • Unconnected block output ports to error • Unconnected line to error

ID: Title	hisl_0306: Configuration Parameters > Diagnostics > Connectivity > Signals
Rationale	Improve robustness of design.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal connectivity • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal connectivity • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal connectivity • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal connectivity • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal connectivity <p>For check details, see “Check safety-related diagnostic settings for signal connectivity” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.e - 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e - 'Low-level requirements conform to standards' • IEC 61508-3, Table A.3 (3) - 'Language subset' • IEC 62304, 5.5.3 - 'Software Unit acceptance criteria' • ISO 26262-6, Table 1 (1b) - 'Use of language subsets' • ISO 26262-6, Table 1 (1f) - 'Use of unambiguous graphical representation' • EN 50128, Table A.4 (11) - 'Language Subset'
See Also	“Model Configuration Parameters: Connectivity Diagnostics” in the Simulink documentation
Last Changed	R2017b

hisl_0307: Configuration Parameters > Diagnostics > Connectivity > Buses

ID: Title	hisl_0307: Configuration Parameters > Diagnostics > Connectivity > Buses
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Connectivity pane, set the Buses parameters as follows:</p> <ul style="list-style-type: none"> • Unspecified bus object at root Output block to error • Element name mismatch to error • Bus signal treated as vector to error • Non-bus signals treated as bus signals to error
Rationale	Improve robustness of design.

ID: Title	hisl_0307: Configuration Parameters > Diagnostics > Connectivity > Buses
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for bus connectivity • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for bus connectivity • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for bus connectivity • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for bus connectivity • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for bus connectivity <p>For check details, see “Check safety-related diagnostic settings for bus connectivity” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b - Software architecture is consistent • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset
See Also	“Model Configuration Parameters: Connectivity Diagnostics” in the Simulink documentation
Last Changed	R2020a

hisl_0308: Configuration Parameters > Diagnostics > Connectivity > Function calls

ID: Title	hisl_0308: Configuration Parameters > Diagnostics > Connectivity > Function calls
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Connectivity pane, set the Function calls parameters as follows:</p> <ul style="list-style-type: none"> • Invalid function-call connection to error • Context-dependent inputs to Enable all as errors
Rationale	Improve robustness of design.

ID: Title	hisl_0308: Configuration Parameters > Diagnostics > Connectivity > Function calls
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings that apply to function-call connectivity • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings that apply to function-call connectivity • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings that apply to function-call connectivity • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings that apply to function-call connectivity • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings that apply to function-call connectivity <p>For check details, see “Check safety-related diagnostic settings that apply to function-call connectivity” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b - Software architecture is consistent • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset
See Also	“Model Configuration Parameters: Connectivity Diagnostics” in the Simulink documentation
Last Changed	R2017b

hisl_0309: Configuration Parameters > Diagnostics > Type Conversion

ID: Title	hisl_0309: Configuration Parameters > Diagnostics > Type Conversion
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Type Conversion pane, set these parameters as follows:</p> <ul style="list-style-type: none"> • Unnecessary type conversion to warning • Vector/matrix block input conversion to error • 32-bit integer to single precision float conversion to warning
Rationale	Improve robustness of design.

ID: Title	hisl_0309: Configuration Parameters > Diagnostics > Type Conversion
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for type conversions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for type conversions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for type conversions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for type conversions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for type conversions <p>For check details, see “Check safety-related diagnostic settings for type conversions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g - Algorithms are accurate • DO-331, Section MB.6.3.2.g - Algorithms are accurate • IEC 61508-3, Table A.3 (2) Strongly typed programming language • IEC 61508-3, Table A.4 (3) Defensive programming • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) Use of language subsets • ISO 26262-6, Table 1 (1c) Enforcement of strong typing • ISO 26262-6, Table 1 (1d) Use of defensive implementation techniques • EN 50128, Table A.4 (8) Strongly Typed Programming Language • EN 50128, Table A.3 (1) Defensive Programming
See Also	“Model Configuration Parameters: Type Conversion Diagnostics” in the Simulink documentation
Last Changed	R2017b

hisl_0310: Configuration Parameters > Diagnostics > Model Referencing

ID: Title	hisl_0310: Configuration Parameters > Diagnostics > Model Referencing
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Model Referencing pane, set these parameters as follows:</p> <ul style="list-style-type: none"> • Port and parameter mismatch to error • Invalid root Inport/Outport block connection to error • Unsupported data logging to error
Rationale	Improve robustness of design.

ID: Title	hisl_0310: Configuration Parameters > Diagnostics > Model Referencing
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model referencing • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model referencing • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model referencing • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model referencing • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for model referencing <p>For check details, see “Check safety-related diagnostic settings for model referencing” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.d - High-level requirements are verifiable • DO-331, Section MB.6.3.2.d - Low-level requirements are verifiable. • DO-331, Section MB.6.3.3.b - Software architecture is consistent • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset
See Also	“Model Configuration Parameters: Model Referencing Diagnostics” in the Simulink documentation
Last Changed	R2020a

hisl_0311: Configuration Parameters > Diagnostics > Stateflow

ID: Title	hisl_0311: Configuration Parameters > Diagnostics > Stateflow
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Stateflow pane, set these parameters:</p> <ul style="list-style-type: none"> • Unexpected backtracking to error • Invalid input data access in chart initialization to error • No unconditional default transitions to error • Transitions outside natural parent to error • Undirected event broadcasts to error • Transition action specified before condition action to error • Unreachable execution path to error
Rationale	Improve robustness of design and promote a clear modeling style.

ID: Title	hisl_0311: Configuration Parameters > Diagnostics > Stateflow
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Stateflow • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Stateflow • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Stateflow • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Stateflow • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for Stateflow <p>For check details, see “Check safety-related diagnostic settings for Stateflow” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.d 'Low-level requirements are verifiable' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • EN 50128, Table A.4 (11) - 'Language Subset' • EN 50128, Table A.12 (6) - 'Limited Use of Recursion' • IEC 62304, 5.5.3 - 'Software Unit acceptance criteria' • ISO 26262-6, Table 1 (1b) - 'Use of language subsets' • ISO 26262-6, Table 8 (1j) - 'No recursions' • IEC 61508-3, Table A.3 (3) - 'Language subset' • MISRA C:2012, Rule 17.2
See Also	“Model Configuration Parameters: Stateflow Diagnostics” in the Simulink documentation
Last Changed	R2018b

hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals

ID: Title	hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals
Description	<p>In the Configuration Parameters dialog box, on the Diagnostics > Data Validity pane, set the Signals parameters as follows:</p> <ul style="list-style-type: none"> • Signal resolution to Explicit only • Division by singular matrix to error • Underspecified data types to error • Inf or NaN block output to error • “rt” prefix for identifiers to error • Wrap on overflow to error • Saturate on overflow to error • Simulation range checking to error
Rationale	Improve robustness of design.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal data • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal data • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal data • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal data • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related diagnostic settings for signal data <p>For check details, see “Check safety-related diagnostic settings for signal data” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.4.2.2 'Robustness Test Cases' • DO-331, Section MB.6.4.3 'Requirements-Based Testing Methods' • DO-331, Section MB.6.3.1.e 'High-level requirements conform to standards' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Dir 4.1

ID: Title	hisl_0314: Configuration Parameters > Diagnostics > Data Validity > Signals
See Also	"Model Configuration Parameters: Data Validity Diagnostics"
Last Changed	R2018a

Model Referencing

hisl_0037: Configuration Parameters > Model Referencing

ID: Title	hisl_0037: Configuration Parameters > Model Referencing	
Description	Set these Configuration Parameters as follows:	
	A	Rebuild to Never or If any changes detected.
	B	Never rebuild diagnostic to Error if rebuild required.
	C	Clear Pass fixed-size scalar root inputs by value for code generation.
	D	Clear Minimize algebraic loop occurrences.
Rationale	A	To prevent unnecessary regeneration of the code, resulting in changing only the date of the file and slowing down the build process when using model references.
	B	For safety-related applications, an error should alert model developers that the parent and referenced models are inconsistent.
	C	To prevent unpredictable data because scalar values can change during a time step.
	D	To be compatible with the recommended setting of Single output / update function for embedded systems code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related model referencing settings • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related model referencing settings • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related model referencing settings • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related model referencing settings • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related model referencing settings <p>For check details, see “Check safety-related model referencing settings” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (3) 'Defensive programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' 	
Last Changed	R2017b	

Simulation Target

hisl_0046: Configuration Parameters > Simulation Target > Block reduction

ID: Title	hisl_0046: Configuration Parameters > Simulation Target > Block reduction
Description	To support unambiguous presentation of the generated code and support traceability between a model and generated code, clear configuration parameter Block reduction .
Notes	Selecting Block reduction might optimize blocks out of the code generated for a model. This results in requirements without associated code and violates traceability objectives.
Rationale	Supports: <ul style="list-style-type: none"> • Unambiguous presentation of generated code • Traceability between a model and generated code
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related block reduction optimization settings • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related block reduction optimization settings • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related block reduction optimization settings • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related block reduction optimization settings • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related block reduction optimization settings <p>For check details, see “Check safety-related block reduction optimization settings” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.4.e ‘Source code is traceable to low-level requirements’ • IEC 61508-3, Clauses 7.4.7.2, 7.4.8.3, and 7.7.2.8 which require to demonstrate that no unintended functionality has been introduced
See Also	“Block reduction” in the Simulink documentation
Last Changed	R2018b

Code Generation

In this section...

“hisl_0051: Configuration Parameters > Code Generation > Optimization > Loop unrolling threshold” on page 5-26

“hisl_0052: Configuration Parameters > Code Generation > Optimization > Data initialization” on page 5-27

“hisl_0053: Configuration Parameters > Code Generation > Optimization > Remove code from floating-point to integer conversions that wraps out-of-range values” on page 5-29

“hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions” on page 5-30

“hisl_0056: Configuration Parameters > Code Generation > Optimization > Optimize using the specified minimum and maximum values” on page 5-31

“hisl_0038: Configuration Parameters > Code Generation > Comments” on page 5-32

“hisl_0039: Configuration Parameters > Code Generation > Interface” on page 5-33

“hisl_0047: Configuration Parameters > Code Generation > Code Style” on page 5-34

“hisl_0049: Configuration Parameters > Code Generation > Identifiers” on page 5-35

hisl_0051: Configuration Parameters > Code Generation > Optimization > Loop unrolling threshold

ID: Title	hisl_0051: Configuration Parameters > Code Generation > Optimization > Loop unrolling threshold
Description	To set the minimum signal or parameter width for generating a for loop, set configuration parameter Loop unrolling threshold to 2 or greater.
Notes	Loop unrolling threshold specifies the array size at which the code generator begins to use a for loop, instead of separate assignment statements, to assign values to the elements of a signal or parameter array. The default value is 5.
Rationale	Support unambiguous generated code.

ID: Title	hisl_0051: Configuration Parameters > Code Generation > Optimization > Loop unrolling threshold
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for Loop unrolling threshold • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for Loop unrolling threshold • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for Loop unrolling threshold • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for Loop unrolling threshold • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for Loop unrolling threshold <p>For check details, see “Check safety-related optimization settings for Loop unrolling threshold” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.4.e—Source code is traceable to low-level requirements. • IEC 61508-3, Table A.3 (3) 'Language Subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • MISRA C:2012, Rule 6.1
See Also	“Loop unrolling threshold” (Simulink Coder) in the Simulink documentation
Last Changed	R2018a

hisl_0052: Configuration Parameters > Code Generation > Optimization > Data initialization

ID: Title	hisl_0052: Configuration Parameters > Code Generation > Optimization > Data initialization	
Description	To support complete definition of data and initialize internal and external data to zero, clear these configuration parameters:	
	A	Remove root level I/O zero initialization.
	B	Remove internal data zero initialization.

ID: Title	hisl_0052: Configuration Parameters > Code Generation > Optimization > Data initialization	
Note	<p>Explicitly initialize all variables. If the run-time environment of the target system provides mechanisms to initialize all I/O and state variables, consider using the initialization of the target as an alternative to the suggested settings.</p> <p>These configuration parameters are applicable only when the System target file is an ERT-based target.</p>	
Rationale	A, B	Support fully defined data in generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data initialization • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data initialization • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data initialization • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data initialization • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data initialization <p>For check details, see “Check safety-related optimization settings for data initialization” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.3.b 'Software architecture is consistent' • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming' 	
See Also	<p>Information about the following parameters in the Simulink documentation:</p> <ul style="list-style-type: none"> • “Remove root level I/O zero initialization” (Embedded Coder) • “Remove internal data zero initialization” (Embedded Coder) 	
Last Changed	R2018b	

hisl_0053: Configuration Parameters > Code Generation > Optimization > Remove code from floating-point to integer conversions that wraps out-of-range values

ID: Title	hisl_0053: Configuration Parameters > Code Generation > Optimization > Remove code from floating-point to integer conversions that wraps out-of-range values
Description	To support verifiable code, select configuration parameter Remove code from floating-point to integer conversions that wraps out-of-range values
Notes	Avoid overflows as opposed to handling them with wrapper code. For blocks whose Saturate on integer overflow configuration parameter is cleared, deselecting Remove code from floating-point to integer conversions that wraps out-of-range values can add code that wraps out of range values, resulting in unreachable code that cannot be tested.
Rationale	Support generation of code that can be verified.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data type conversions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data type conversions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data type conversions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data type conversions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for data type conversions <p>For check details, see “Check safety-related optimization settings for data type conversions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Rule 2.1
See Also	“Remove code from floating-point to integer conversions that wraps out-of-range values” (Simulink Coder) in the Simulink documentation
Last Changed	R2018b

hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions

ID: Title	hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions
Description	To support the robustness of the operations, clear configuration parameter Remove code that protects against division arithmetic exceptions .
Note	<p>Avoid division-by-zero exceptions. If you clear Remove code that protects against division arithmetic exceptions, the code generator produces code that guards against division by zero for fixed-point data.</p> <p>This configuration parameter is applicable only when the System target file is an ERT-based target.</p>
Rationale	Protect against divide-by-zero exceptions for fixed-point code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for division arithmetic exceptions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for division arithmetic exceptions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for division arithmetic exceptions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for division arithmetic exceptions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for division arithmetic exceptions <p>For check details, see “Check safety-related optimization settings for division arithmetic exceptions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.g 'Algorithms are accurate' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • IEC 61508-3, Table A.3 (3) 'Language Subset' • IEC 61508-3 Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1(b) 'Use of language subsets' • ISO 26262-6, Table 1(d) 'Use of defensive implementation techniques' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.3 (1) 'Defensive Programming' • MISRA C:2012, Dir 4.1
See Also	“Remove code that protects against division arithmetic exceptions” (Embedded Coder) in the Simulink documentation

ID: Title	hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions
Last Changed	R2018b

hisl_0056: Configuration Parameters > Code Generation > Optimization > Optimize using the specified minimum and maximum values

ID: Title	hisl_0056: Configuration Parameters > Code Generation > Optimization > Optimize using the specified minimum and maximum values
Description	To support verifiable code, clear configuration parameter Optimize using the specified minimum and maximum values .
Notes	Selecting Optimize using the specified minimum and maximum values can result in requirements without associated code and violates traceability objectives.
Rationale	Support traceability between a model and generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related optimization settings for specified minimum and maximum values • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related optimization settings for specified minimum and maximum values • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related optimization settings for specified minimum and maximum values • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related optimization settings for specified minimum and maximum values • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related optimization settings for specified minimum and maximum values <p>For check details, see “Check safety-related optimization settings for specified minimum and maximum values” (Simulink Check)</p>
References	<ul style="list-style-type: none"> • DO-331 Section MB.MB.6.3.4.e 'Source code is traceable to low-level requirements' • IEC 61508-3, Table A.4 (3) 'Defensive Programming' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1d) 'Use of defensive implementation techniques' • EN 50128, Table A.3 (1) 'Defensive Programming'
See also	<ul style="list-style-type: none"> • “Optimize using the specified minimum and maximum values” (Embedded Coder) • Radio Technical Commission for Aeronautics (RTCA) for information on the DO-178C Software Considerations in Airborne Systems and Equipment Certification and related standards
Last Changed	R2018b

hisl_0038: Configuration Parameters > Code Generation > Comments

ID: Title	hisl_0038: Configuration Parameters > Code Generation > Comments	
Description	In the Configuration Parameters dialog box, on the Code Generation > Comments pane, select these parameters:	
	A	Include comments.
	B	Simulink block comments.
	C	Show eliminated blocks.
	D	Verbose comments for 'Model default' storage class.
	E	Requirements in block comments.
Rationale	A	Including comments provides good traceability between the code and the model.
	B	Including comments that describe the code for blocks provides good traceability between the code and the model.
	C	Including comments that describe the code for blocks eliminated from a model provides good traceability between the code and the model.
	D	Including the names of parameter variables and source blocks as comments in the model parameter structure declaration in <i>model_prm.h</i> provides good traceability between the code and the model.
	E	Including requirement descriptions assigned to Simulink blocks as comments provides good traceability between the code and the model.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related code generation settings for comments • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related code generation settings for comments • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related code generation settings for comments • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related code generation settings for comments • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related code generation settings for comments <p>For check details, see “Check safety-related code generation settings for comments” (Simulink Check).</p>	
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.4.e 'Source code is traceable to low-level requirements' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1e) 'Use of well-trusted design principles' • EN 50128, Table A.4 (11) 'Language Subset' 	
Last Changed	R2017b	

hisl_0039: Configuration Parameters > Code Generation > Interface

ID: Title	hisl_0039: Configuration Parameters > Code Generation > Interface	
Description	For models used to develop high-integrity systems, in the Configuration Parameters dialog box, on the Code Generation > Interface pane, set the Software environment , Code interface , and Data exchange interface parameters as follows:	
	A	Clear Support: non-finite numbers .
	B	Clear Support: absolute time .
	C	Clear Support: continuous time .
	D	Clear Support: non-inlined S-functions .
	E	Clear Classic call interface .
	F	Select Single output / update function .
	G	Clear Terminate function required .
	H	Select Remove error status field in real-time model data structure .
	I	Clear MAT-file logging .
Rationale	A	Support for non-finite numbers is not recommended for real-time safety-related systems.
	B	Support for absolute time is not recommended for real-time safety-related systems.
	C	Support for continuous time is not recommended for real-time safety-related systems.
	D	Support for non-inlined S-functions requires support of non-finite numbers, which is not recommended for real-time safety-related systems.
	E	To eliminate model function calls compatible with the main program module of the pre-2012a GRT target that is not recommended for real-time safety-related systems; use an ERT based target instead.
	F	To simplify the interface to the real-time operating system (RTOS) and simplify verification of the generated code by creating a single call to both the output and update functions.
	G	To eliminate <i>model_terminate</i> function, which is not recommended for real-time safety-related systems.
	H	To eliminate extra code for logging and monitoring error status that might not be reachable for testing.
	I	To eliminate extra code for logging test points to a MAT file that is not supported by embedded targets.

ID: Title	hisl_0039: Configuration Parameters > Code Generation > Interface
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related code generation interface settings • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related code generation interface settings • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related code generation interface settings • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related code generation interface settings • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related code generation interface settings <p>For check details, see “Check safety-related code generation interface settings” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.c 'High-level requirements are compatible with target computer' • DO-331, Section MB.6.3.2.c 'Low-level requirements are compatible with target computer' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset'
Last Changed	R2018b

hisl_0047: Configuration Parameters > Code Generation > Code Style

ID: Title	hisl_0047: Configuration Parameters > Code Generation > Code Style	
Description	In the Configuration Parameters dialog box, on the Code Generation > Code Style pane, set these parameters:	
	A	Set Parenthesis level to Maximum (Specify precedence with parentheses).
Rationale	A	To prevent unexpected results.
	B	To improve traceability of the generated code.

ID: Title	hisl_0047: Configuration Parameters > Code Generation > Code Style
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related code generation settings for code style • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related code generation settings for code style • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related code generation settings for code style • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related code generation settings for code style • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related code generation settings for code style <p>For check details, see “Check safety-related code generation settings for code style” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.c 'High-level requirements are compatible with target computer' • DO-331, Section MB.6.3.2.c 'Low-level requirements are compatible with target computer' • DO-331, Section MB.6.3.4.e 'Source code is traceable to low-level requirements' • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' • MISRA C:2012, Rule 12.1
Last Changed	R2019b

hisl_0049: Configuration Parameters > Code Generation > Identifiers

ID: Title	hisl_0049: Configuration Parameters > Code Generation > Identifiers
Description	To minimize the likelihood that parameter and signal names will change during code generation when the model changes, set configuration parameter Minimum mangle length to 4 or greater.
Rationale	Decrease the effort to perform code review.

ID: Title	hisl_0049: Configuration Parameters > Code Generation > Identifiers
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Configuration > Check safety-related code generation identifier settings • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Configuration > Check safety-related code generation identifier settings • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Configuration > Check safety-related code generation identifier settings • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Configuration > Check safety-related code generation identifier settings • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Configuration > Check safety-related code generation identifier settings <p>For check details, see “Check safety-related code generation identifier settings” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.4.e ‘Source code is traceable to low-level requirements’ • IEC 61508-3, Table A.3 (3) ‘Language subset’ • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) ‘Use of language subsets’ • EN 50128, Table A.4 (11) ‘Language Subset’
Last Changed	R2019a

Naming Considerations

Naming Considerations

In this section...
“hisl_0031: Model file names” on page 6-2
“hisl_0032: Model object names” on page 6-3

hisl_0031: Model file names

ID: Title	hisl_0031: Model file names
Description	<p>For model file names:</p> <ul style="list-style-type: none"> • Use these characters: a-z, A-Z, 0-9, and the underscore (_). • Use strings that are more than 2 and less than 64 characters. (<i>Not including the dot and file extension</i>). <p>Do not:</p> <ul style="list-style-type: none"> • Start the name with a number. • Use underscores at the beginning or end of a string. • Use more than one consecutive underscore. • Use underscores in file extensions. • Use reserved identifiers.
Rationale	<ul style="list-style-type: none"> • Readability • Compiler limitations • Model-to-generated code traceability
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Naming > Check model file name • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Naming > Check model file name • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Naming > Check model file name • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Naming > Check model file name • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Naming > Check model file name <p>For check details, see “Check model file name” (Simulink Check).</p>
See Also	<ul style="list-style-type: none"> • MAB guideline ar_0001: Usable characters for file names • MAB guideline ar_0002: Usable characters for folder names • “Reserved Keywords” (Embedded Coder)
References	ISO 26262-6, Table 1 (1h) 'Use of naming conventions'
Last Changed	R2018b

ID: Title	hisl_0031: Model file names
Examples	<p>Recommended</p> <ul style="list-style-type: none"> • My_model.slx <p>Not Recommended</p> <ul style="list-style-type: none"> • _My_model.slx • 2018_01_11_model.slx • New.slx

hisl_0032: Model object names

ID: Title	hisl_0032: Model object names
Description	<p>For the following model object names:</p> <ul style="list-style-type: none"> • Signals • Parameters • Blocks • Named Stateflow objects (States, Boxes, Simulink Functions, Graphical Functions, Truth Tables) <p>Use:</p> <ul style="list-style-type: none"> • These characters: a-z, A-Z, 0-9, and the underscore (_). • Strings that are fewer than 32 characters. <p>Do not:</p> <ul style="list-style-type: none"> • Start the name with a number. • Use underscores at the beginning or end of a string. • Use more than one consecutive underscore. • Use reserved identifiers.

ID: Title	hisl_0032: Model object names
Notes	Reserved names: <ul style="list-style-type: none"> • MATLAB keywords • Reserved keywords for C, C++, and code generation. For complete list, see “Reserved Keywords” (Simulink Coder). • <code>int8</code>, <code>uint8</code> • <code>int16</code>, <code>uint16</code> • <code>int32</code>, <code>uint32</code> • <code>inf</code>, <code>Inf</code> • <code>NaN</code>, <code>nan</code> • <code>eps</code> • <code>intmin</code>, <code>intmax</code> • <code>realmin</code>, <code>realmax</code> • <code>pi</code> • <code>infinity</code> • <code>Nil</code>
Rationale	<ul style="list-style-type: none"> • Readability • Compiler limitations • Model-to-generated code traceability
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Naming > Check model object names <p>For check details, see “Check model object names” (Simulink Check).</p>
See Also	MAB guidelines: <ul style="list-style-type: none"> • <code>jc_0201</code>: Usable characters for subsystem namesM • <code>jc_0211</code>: Usable characters for Inport blocks and Outport block • <code>jc_0231</code>: Usable characters for block names • <code>na_0019</code>: Restricted variable names
References	<ul style="list-style-type: none"> • MISRA C:2012, Rule 21.2 • ISO 26262-6, Table 1 (1h) 'Use of naming conventions'
Last Changed	R2018b

ID: Title	hisl_0032: Model object names
Example	<p data-bbox="360 298 1490 340">Recommended</p> <ul data-bbox="360 348 1490 432" style="list-style-type: none"><li data-bbox="360 348 1490 390">• Block name: My_Controller<li data-bbox="360 390 1490 432">• Signal name: a_b <p data-bbox="360 449 1490 491">Not Recommended</p> <ul data-bbox="360 499 1490 583" style="list-style-type: none"><li data-bbox="360 499 1490 541">• Block name: My Controller<li data-bbox="360 541 1490 583">• Signal name: 12a__b

MISRA C:2012 Compliance Considerations

- “Modeling Style” on page 7-2
- “Block Usage” on page 7-12
- “Configuration Settings” on page 7-18
- “Stateflow Chart Considerations” on page 7-20

Modeling Style

In this section...

“hisl_0032: Model object names” on page 7-2

“hisl_0061: Unique identifiers for clarity” on page 7-4

“hisl_0062: Global variables in graphical functions” on page 7-8

“hisl_0063: Length of user-defined object names to improve MISRA C:2012 compliance” on page 7-10

hisl_0032: Model object names

ID: Title	hisl_0032: Model object names
Description	<p>For the following model object names:</p> <ul style="list-style-type: none"> • Signals • Parameters • Blocks • Named Stateflow objects (States, Boxes, Simulink Functions, Graphical Functions, Truth Tables) <p>Use:</p> <ul style="list-style-type: none"> • These characters: a - z, A - Z, 0 - 9, and the underscore (_). • Strings that are fewer than 32 characters. <p>Do not:</p> <ul style="list-style-type: none"> • Start the name with a number. • Use underscores at the beginning or end of a string. • Use more than one consecutive underscore. • Use reserved identifiers.

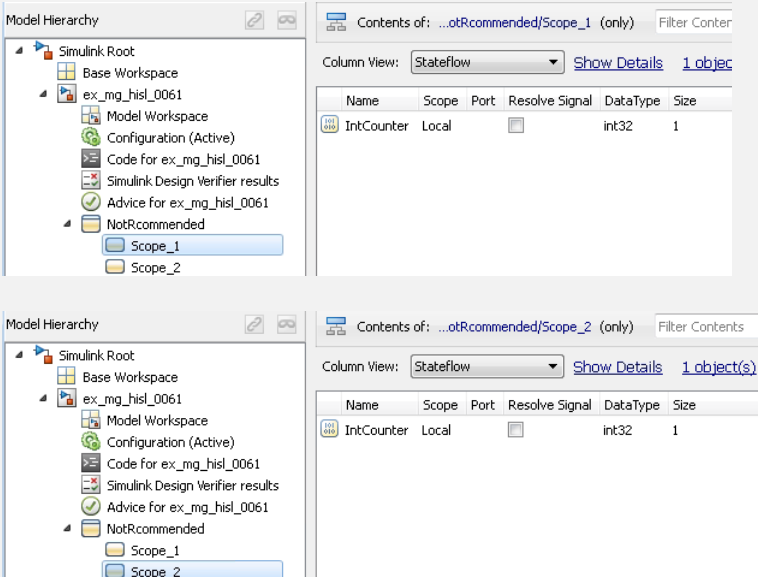
ID: Title	hisl_0032: Model object names
Notes	Reserved names: <ul style="list-style-type: none"> • MATLAB keywords • Reserved keywords for C, C++, and code generation. For complete list, see “Reserved Keywords” (Simulink Coder). • int8 , uint8 • int16, uint16 • int32, uint32 • inf, Inf • NaN, nan • eps • intmin, intmax • realmin, realmax • pi • infinity • Nil
Rationale	<ul style="list-style-type: none"> • Readability • Compiler limitations • Model-to-generated code traceability
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Naming > Check model object names • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Naming > Check model object names <p>For check details, see “Check model object names” (Simulink Check).</p>
See Also	MAB guidelines: <ul style="list-style-type: none"> • jc_0201: Usable characters for subsystem namesM • jc_0211: Usable characters for Inport blocks and Outport block • jc_0231: Usable characters for block names • na_0019: Restricted variable names
References	<ul style="list-style-type: none"> • MISRA C:2012, Rule 21.2 • ISO 26262-6, Table 1 (1h) 'Use of naming conventions'
Last Changed	R2018b

ID: Title	hisl_0032: Model object names
Example	<p>Recommended</p> <ul style="list-style-type: none"> Block name: My_Controller Signal name: a_b <p>Not Recommended</p> <ul style="list-style-type: none"> Block name: My Controller Signal name: 12a__b

hisl_0061: Unique identifiers for clarity

ID: Title	hisl_0061: Unique identifiers for clarity	
Description	When developing a model:	
	A	Use unique identifiers for Simulink signals.
	B	Define unique identifiers across multiple scopes within a chart.
Notes	The code generator resolves conflicts between identifiers so that symbols in the generated code are unique. The process is called name mangling.	
Rationale	A, B	Improve readability of a graphical model and mapping between identifiers in the model and generated code.
Model Advisor Check	<ul style="list-style-type: none"> By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow charts for uniquely defined data objects By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow charts for uniquely defined data objects By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow charts for uniquely defined data objects By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow charts for uniquely defined data objects By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow charts for uniquely defined data objects <p>For check details, see “Check Stateflow charts for uniquely defined data objects” (Simulink Check).</p>	

ID: Title	hisl_0061: Unique identifiers for clarity
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (2) 'Strongly typed programming language' • IEC 61508-3, Table A.3 (3) - Language subset • IEC 61508-3, Table A.4 (5) - Design and coding standards • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - 'Use of language subsets' • ISO 26262-6, Table 1 (1c) 'Enforcement of strong typing' • ISO 26262-6, Table 1 (1d) - 'Use of defensive implementation techniques' • ISO 26262-6, Table 1 (1e) - 'Use of well-trusted design principles' • ISO 26262-6, Table 1 (1f) - 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1g) - 'Use of style guides' • ISO 26262-6, Table 1 (1h) - 'Use of naming conventions' • EN 50128, Table A.3 (1) - Defensive Programming • EN 50128, Table A.4 (8) 'Strongly Typed Programming Language' • EN 50128, Table A.4 (11) - 'Language Subset' • EN 50128, Table A.12 (1) 'Coding Standard' • EN 50128, Table A.12 (2) 'Coding Style Guide'
See Also	"Code Appearance" (Simulink Coder)
Last Changed	R2017b

ID: Title	hisl_0061: Unique identifiers for clarity
Examples	<p>Not Recommended</p> <p>In the following example, two states Scope_1 and Scope_2 use local identifier IntCounter.</p> <div style="border: 1px dashed black; padding: 10px; margin: 10px 0;"> <p>Scope_1</p> <p>% IntCounter is defined at this scope</p> <p>entry:</p> <p>IntCounter = int32(0);</p> <p>during:</p> <p>Chart_Level_Output_S1 = Chart_Level_Input + IntCounter;</p> <p>IntCounter = IntCounter + int32(1);</p> </div> <div style="border: 1px dashed black; padding: 10px; margin: 10px 0;"> <p>Scope_2</p> <p>% IntCounter is defined at this scope</p> <p>entry:</p> <p>IntCounter = int32(0);</p> <p>during:</p> <p>Chart_Level_Output_S2 = Chart_Level_Input + IntCounter;</p> <p>IntCounter = IntCounter + int32(1);</p> </div> <p>The identifier IntCounter is defined for two states, Scope_1 and Scope_2.</p> 

ID: Title **his1_0061: Unique identifiers for clarity**

Recommended

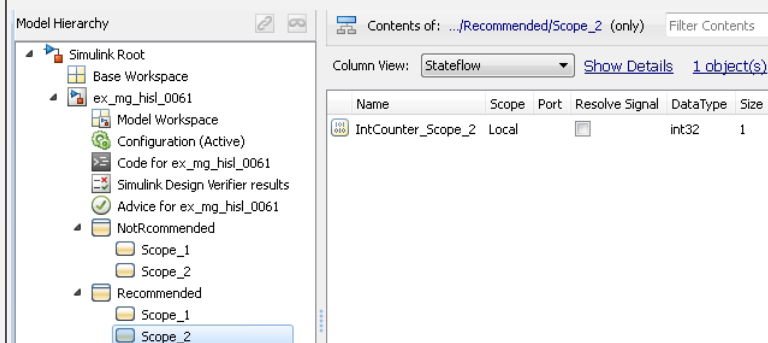
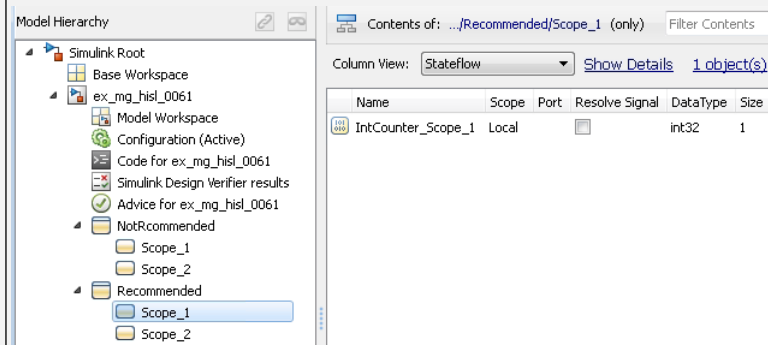
To clarify the model, create unique identifiers. In the following example, state Scope_1 uses local identifier IntCounter_Scope_1. State Scope_2 uses local identifier IntCounter_Scope_2.

```

Scope_1
% IntCounter_Scope_1 is defined at this scope
entry:
  IntCounter_Scope_1 = int32(0);
during:
  Chart_Level_Output_S1 = Chart_Level_Input + IntCounter_Scope_1;
  IntCounter_Scope_1 = IntCounter_Scope_1 + int32(1);

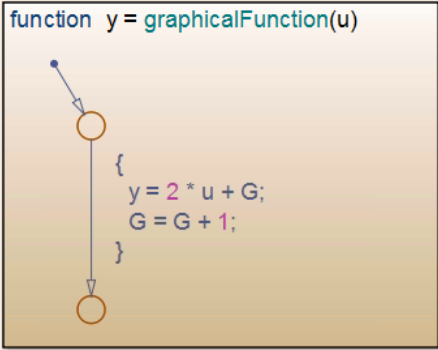
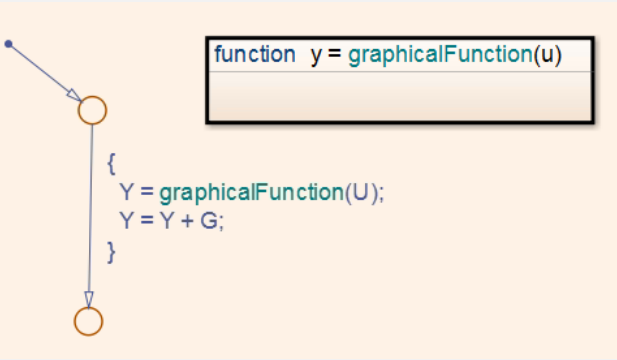
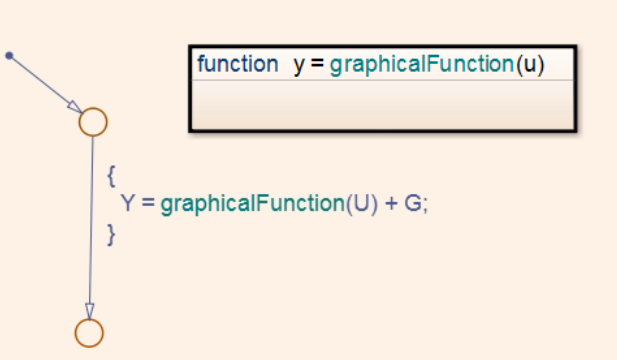
Scope_2
% IntCounter_Scope_2 is defined at this scope
entry:
  IntCounter_Scope_2 = int32(0);
during:
  Chart_Level_Output_S2 = Chart_Level_Input + IntCounter_Scope_2;
  IntCounter_Scope_2 = IntCounter_Scope_2 + int32(1);
    
```

The identifier IntCounter_Scope_1 is defined for state Scope_1. Identifier IntCounter_Scope_2 is defined for Scope_2.



hisl_0062: Global variables in graphical functions

ID: Title	hisl_0062: Global variables in graphical functions
Description	For data with a global scope used in a function, do not use the data in the calling expression if a value is assigned to the data in that function.
Rationale	Enhance readability of a model by removing ambiguity in the values of global variables.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check global variables in graphical functions • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check global variables in graphical functions • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check global variables in graphical functions • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check global variables in graphical functions • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check global variables in graphical functions <p>For check details, see “Check global variables in graphical functions” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • IEC 61508-3, Table A.4 (4) 'Modular approach' • IEC 61508-3, A.4 (5) 'Design and coding standards' • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • ISO 26262-6, Table 1 (1f) 'Use of unambiguous graphical representation' • ISO 26262-6, Table 1 (1h) 'Use of naming conventions' • EN 50128, Table A.4 (11) 'Language Subset' • EN 50128, Table A.12 (1) 'Coding Standard' • EN 50128, Table A.12 (2) 'Coding Style Guide' • DO-331, Section MB.6.3.2.g 'Algorithms are accurate' • MISRA C:2012, Rule 13.2 • MISRA C:2012, Rule 13.5
Last Changed	R2018b

ID: Title	hisl_0062: Global variables in graphical functions
Examples	<p data-bbox="480 300 1417 359">Consider a graphical function <code>graphicalFunction</code> that modifies the global data <code>G</code>.</p> <div data-bbox="505 411 940 758" style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <pre data-bbox="513 422 932 747">function y = graphicalFunction(u) { y = 2 * u + G; G = G + 1; } </pre>  </div> <p data-bbox="480 806 678 835">Recommended</p> <div data-bbox="496 863 1109 1220" style="border: 1px solid black; padding: 10px; margin-bottom: 10px;"> <pre data-bbox="699 898 1084 1125">function y = graphicalFunction(u) { Y = graphicalFunction(U); Y = Y + G; } </pre>  </div> <p data-bbox="480 1255 735 1285">Not Recommended</p> <div data-bbox="496 1312 1109 1669" style="border: 1px solid black; padding: 10px;"> <pre data-bbox="683 1360 1068 1566">function y = graphicalFunction(u) { Y = graphicalFunction(U) + G; } </pre>  </div>

hisl_0063: Length of user-defined object names to improve MISRA C:2012 compliance

ID: Title	hisl_0063: Length of user-defined object names to improve MISRA C:2012 compliance	
Description	<p>To improve MISRA C:2012 compliance of generated code, use configuration parameter Maximum identifier length (MaxIdLength) to limit the length of user defined names.</p>	
<p>Note The default of Maximum identifier length is 31.</p>		
<p>A For Subsystem blocks with parameter Function name options set to User specified, limit the length of function names to be equal to or less than the value specified in Maximum identifier length.</p>		
<p>B Limit the length of data object names to be equal to or less than the value specified in Maximum identifier length:</p> <ul style="list-style-type: none"> • Simulink.AliasType • Simulink.NumericType • Simulink.Variant • Simulink.Bus • Simulink.BusElement • Simulink.IntEnumType 		
<p>C When using these storage classes, limit the length of signal and parameter names to be equal to or less than the value specified in Maximum identifier length:</p> <ul style="list-style-type: none"> • Exported Global • Imported Extern • Imported Extern Pointer • Custom storage class 		
<p>Note If specified, this includes the length of the Identifier name.</p>		
Rationale	Length in the generated code can result in a MISRAC:2012 violation.	

ID: Title	hisl_0063: Length of user-defined object names to improve MISRA C:2012 compliance
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for length of user-defined object names • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for length of user-defined object names • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for length of user-defined object names • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for length of user-defined object names • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for length of user-defined object names <p>For check details, see “Check for length of user-defined object names” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • MISRA C:2012, Rule 5.1 • MISRA C:2012, Rule 5.2 • MISRA C:2012, Rule 5.3 • MISRA C:2012, Rule 5.4 • MISRA C:2012, Rule 5.5
Prerequisites	“hisl_0060: Configuration parameters that improve MISRA C:2012 compliance” on page 7-18
Last Changed	R2018b

Block Usage

In this section...
"hisl_0020: Blocks not recommended for MISRA C:2012 compliance" on page 7-12
"hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance" on page 7-14
"hisl_0102: Data type of loop control variables to improve MISRA C:2012 compliance" on page 7-16

hisl_0020: Blocks not recommended for MISRA C:2012 compliance

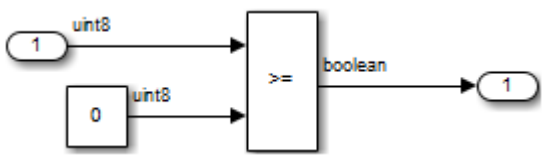
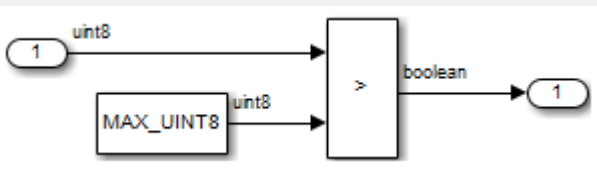
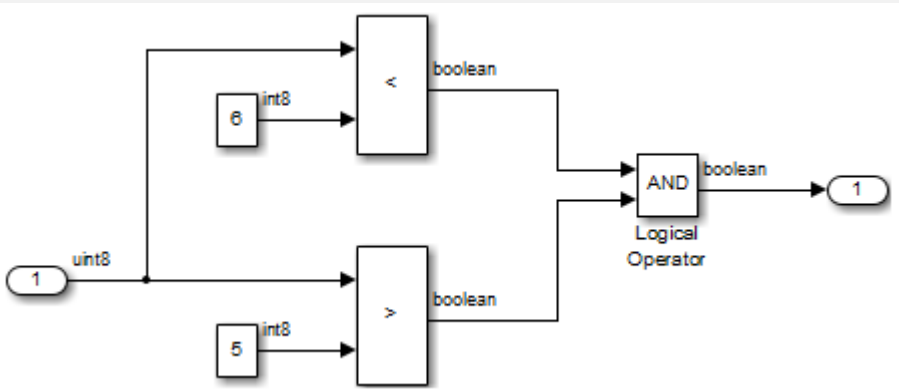
ID: Title	hisl_0020: Blocks not recommended for MISRA C:2012 compliance	
Description	To improve MISRA C:2012 compliance of the generated code:	
	A	Use only blocks that support code generation, as documented in the Simulink Block Support Table.
	B	Do not use blocks that are listed as "Not recommended for production code" in the Simulink Block Support Table.
	C	Do not use Lookup Table blocks using cubic spline interpolation or extrapolation methods. Specific blocks are: <ul style="list-style-type: none"> • 1-D Lookup Table • 2-D Lookup Table • n-D Lookup Table
	D	Do not use deprecated Lookup Table blocks. The deprecated Lookup Table blocks are Lookup and Lookup2D.
	E	Do not use S-Function Builder blocks in the model or subsystem.
	F	Do not use From Workspace blocks in the model or subsystem.
	G	Do not use these String blocks in the model or subsystem: <ul style="list-style-type: none"> • Compose String • Scan String • String to Single • String to Double • To String
Notes	If you follow this and other modeling guidelines, you can eliminate model constructs that are not suitable for C/C++ production code generation, at the same time, increase the likelihood of generating code that complies with the MISRA C:2012 standard.	
	Use the Block Support Table block to view the Block Support Table. Blocks with the footnote (4) in the Block Support Table are classified as "Not recommended for production code".	
Rationale	A, B, C, D, E, F, G	Improve quality and MISRA C:2012 compliance of the generated code.

ID: Title	hisl_0020: Blocks not recommended for MISRA C:2012 compliance
Model Advisor Checks	<p>To check model for conditions A,B,C, D, E, F, and G:</p> <ul style="list-style-type: none"> • By Task > Modeling Guidelines for MISRA C:2012 > Code > Check for blocks not recommended for MISRA C:2012 • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Code > Check for blocks not recommended for MISRA C:2012 • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Code > Check for blocks not recommended for MISRA C:2012 • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Code > Check for blocks not recommended for MISRA C:2012 • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Code > Check for blocks not recommended for MISRA C:2012 • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Code > Check for blocks not recommended for MISRA C:2012 <p>For check details, see “Check for blocks not recommended for MISRA C:2012” (Simulink Check).</p>
	<p>To check model for conditions A and B:</p> <ul style="list-style-type: none"> • By Task > Modeling Guidelines for MISRA C:2012 > Check for blocks not recommended for C/C++ production code deployment • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check for blocks not recommended for C/C++ production code deployment • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check for blocks not recommended for C/C++ production code deployment • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check for blocks not recommended for C/C++ production code deployment • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check for blocks not recommended for C/C++ production code deployment • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check for blocks not recommended for C/C++ production code deployment <p>For check details, see “Check for blocks not recommended for C/C++ production code deployment” (Simulink Check).</p>

ID: Title	hisl_0020: Blocks not recommended for MISRA C:2012 compliance
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • DO-331, Section MB.6.3.2.e 'Low-level requirements conform to standards' • DO-331, Section MB.6.3.4.d 'Source code conforms to standards' • IEC 61508-3, Table A.3 (3) - Language subset • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) - Use of language subsets • EN 50128, Table A.4 (11) - Language Subset • MISRA C: 2012
Last Changed	R2018b

hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance

ID: Title	hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance
Description	<p>To improve MISRA C:2012 compliance of generated code, avoid comparison operations with invariant results. Comparison operations are performed by the following blocks:</p> <ul style="list-style-type: none"> • If • Logic • Relational Operator • Switch • Switch Case • Compare to Constant
Note	<p>You can use the design error detection functionality in Simulink Design Verifier to perform the analysis. For more information, see "Dead Logic Detection" (Simulink Design Verifier). If you have a Simulink Design Verifier license, you can use Model Advisor check Detect Dead Logic.</p>
Rationale	<p>Improve MISRA C:2012 compliance of the generated code.</p>
References	<ul style="list-style-type: none"> • MISRA C:2012, Rule 14.3 • MISRA C:2012, Rule 2.1
Last Changed	R2018a

ID: Title	hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance
Example	<p>Invariant comparisons can occur in simple or compound comparison operations. In compound comparison operations, the individual components can be variable when the full calculation is invariant.</p> <p>Simple: A uint8 is always greater than or equal to 0.</p>  <p>Simple: A uint8 cannot have a value greater than 256</p>  <p>Compound: The comparison operations are mutually exclusive</p>  <p>Stateflow :</p>

ID: Title	hisl_0101: Avoid invariant comparison operations to improve MISRA C:2012 compliance
	<p>The diagram illustrates the MISRA C:2012 compliance issue hisl_0101. The top part shows a block diagram where 'uint8(1)' values are assigned to 'prima' and 'seconda', and a 'V' variable is assigned to 'out'. The bottom part shows a state transition diagram with nodes A, A1, and A2. Transitions are labeled with conditions like '[prima==1]' and '[seconda==1]', which are invariant comparisons.</p>

hisl_0102: Data type of loop control variables to improve MISRA C:2012 compliance

ID: Title	hisl_0102: Data type of loop control variables to improve MISRA C:2012 compliance
Description	<p>To improve MISRA C:2012 compliance of generated code, use integer data type for variables that are used as loop control counter variables in:</p> <ul style="list-style-type: none"> • For loops constructed in Stateflow and MATLAB. • For Iterator blocks.
Rationale	<p>Improve MISRA C:2012 compliance of the generated code.</p>

ID: Title	hisl_0102: Data type of loop control variables to improve MISRA C:2012 compliance
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Simulink > Check data type of loop control variables • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Simulink > Check data type of loop control variables • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Simulink > Check data type of loop control variables • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Simulink > Check data type of loop control variables • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Simulink > Check data type of loop control variables <p>For check details, see “Check data type of loop control variables” (Simulink Check)</p>
References	<ul style="list-style-type: none"> • MISRA C:2012, Rule 14.1
Last Changed	R2018a

Configuration Settings

hisl_0060: Configuration parameters that improve MISRA C:2012 compliance

ID: Title	hisl_0060: Configuration parameters that improve MISRA C:2012 compliance
Description	<p>Set these model configuration parameters as specified:</p> <ul style="list-style-type: none"> • System target file as an ERT-based target • Use division for fixed-point net slope computation to On or Use division for reciprocals of integers only. • Inf or NaN block output to warning or error. • Model Verification block enabling to Disable All • Undirected event broadcasts to error. • Wrap on overflow to warning or error. • Production hardware signed integer division rounds to to Zero or Floor • Compile-time recursion limit for MATLAB functions to 0. • Casting Modes to Standards Compliant. • Code replacement library to None or AUTOSAR 4.0 • Maximum identifier length to the implementation dependent limit. The default is 31. • Parentheses level to Maximum (Specify precedence with parentheses) • Shared code placement to Shared location. • Standard math library to C89/C90 (ANSI) or C99 (ISO), depending on the toolchain. • Bitfield declarator type specifier to uint_T when any of these parameters are selected: <ul style="list-style-type: none"> • Pack Boolean data into bitfields • Use bitsets for storing state configuration • Use bitsets for storing Boolean data <p>Select (on) these configuration parameters:</p> <ul style="list-style-type: none"> • Include Comments • MATLAB user comments • Preserve static keyword in function declarations (Select only when configuration parameter File packaging format is set to Compact or CompactWithDataFile.) <p>Deselect (off) these configuration parameters:</p> <ul style="list-style-type: none"> • Shift right on a signed integer as arithmetic shift • Dynamic memory allocation in MATLAB functions • Enable run-time recursion for MATLAB functions

ID: Title	hisl_0060: Configuration parameters that improve MISRA C:2012 compliance
	<ul style="list-style-type: none"> • External mode • Generate shared constants • MAT-file logging • Replace multiplications by powers of two with signed bitwise shifts • Support complex numbers (Only if you do not need complex number support) • Support continuous time • Support non-finite numbers • Support non-inlined S-functions • Use dynamic memory allocation for model initialization (Keep this parameter selected only when configuration parameter Code Interface Packaging is set to Reusable Function.
Rationale	Improve MISRA C:2012 compliance of the generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Code > Check configuration parameters for MISRA C:2012 • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Code > Check configuration parameters for MISRA C:2012 • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Code > Check configuration parameters for MISRA C:2012 • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Code > Check configuration parameters for MISRA C:2012 • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Code > Check configuration parameters for MISRA C:2012 • By Task > Modeling Guidelines for MISRA C:2012 > Check configuration parameters for MISRA C:2012 <p>For High-Integrity System Modeling, see “Check configuration parameters for MISRA C:2012” (Simulink Check).</p> <p>For Modeling Guidelines for MISRA C:2012, see “Check configuration parameters for MISRA C:2012” (Simulink Check)</p>
References	<ul style="list-style-type: none"> • IEC 61508-3, Table A.3 (3) 'Language subset' • ISO 26262-6, Table 1 (1b) 'Use of language subsets' • EN 50128, Table A.4 (11) 'Language Subset' • MISRA C:2012
Last Changed	R2019a

Stateflow Chart Considerations

In this section...

“hisf_0064: Shift operations for Stateflow data to improve code compliance” on page 7-20

“hisf_0065: Type cast operations in Stateflow to improve code compliance” on page 7-21

“hisf_0211: Protect against use of unary operators in Stateflow Charts to improve code compliance” on page 7-22

“hisf_0213: Protect against divide-by-zero calculations in Stateflow charts to improve MISRA C:2012 compliance” on page 7-23

hisf_0064: Shift operations for Stateflow data to improve code compliance

ID: Title	hisf_0064: Shift operations for Stateflow data to improve code compliance	
Description	To improve code compliance of the generated code with Stateflow bit-shifting operations, do not perform:	
	A	Right-shift operations greater than the bit-width of the input type, or by a negative value.
	B	Left-shift operations greater than the bit-width of the output type, or by a negative value.
Note	If you follow this and other modeling guidelines, you increase the likelihood of generating code that complies with the coding standards.	
Rationale	To avoid shift operations in the generated code that might be a coding standard violation.	
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check usage of shift operations for Stateflow data • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check usage of shift operations for Stateflow data • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check usage of shift operations for Stateflow data • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check usage of shift operations for Stateflow data • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check usage of shift operations for Stateflow data <p>For check details, see “Check usage of shift operations for Stateflow data” (Simulink Check).</p>	

ID: Title	hisf_0064: Shift operations for Stateflow data to improve code compliance
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (2) Strongly typed programming language • IEC 61508-3, Table A.4 (3) Defensive programming • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) Use of language subsets • ISO 26262-6, Table 1 (1c) Enforcement of strong typing • ISO 26262-6, Table 1 (1d) Use of defensive implementation techniques • EN 50128, Table A.4 (8) Strongly Typed Programming Language • EN 50128, Table A.3 (1) Defensive Programming
Prerequisites	"hisf_0060: Configuration parameters that improve MISRA C:2012 compliance" on page 7-18
Last Changed	R2017b

hisf_0065: Type cast operations in Stateflow to improve code compliance

ID: Title	hisf_0065: Type cast operations in Stateflow to improve code compliance
Description	In Stateflow charts that use the C action language, use the := notation to protect against Stateflow casting integer and fixed-point calculations to wider data types than the input data types.
Note	If you follow this and other modeling guidelines, you increase the likelihood of generating code that complies with the coding standards.
Rationale	To avoid implicit casts in the generated code that might violate coding standards.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check assignment operations in Stateflow Charts • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check assignment operations in Stateflow Charts • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check assignment operations in Stateflow Charts • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check assignment operations in Stateflow Charts • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check assignment operations in Stateflow Charts <p>For check details, see "Check assignment operations in Stateflow Charts" (Simulink Check).</p>

ID: Title	hisf_0065: Type cast operations in Stateflow to improve code compliance
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (2) Strongly typed programming language • IEC 61508-3, Table A.4 (3) Defensive programming • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) Use of language subsets • ISO 26262-6, Table 1 (1c) Enforcement of strong typing • ISO 26262-6, Table 1 (1d) Use of defensive implementation techniques • EN 50128, Table A.4 (8) Strongly Typed Programming Language • EN 50128, Table A.3 (1) Defensive Programming
Prerequisites	"hisl_0060: Configuration parameters that improve MISRA C:2012 compliance" on page 7-18
Last Changed	R2017b

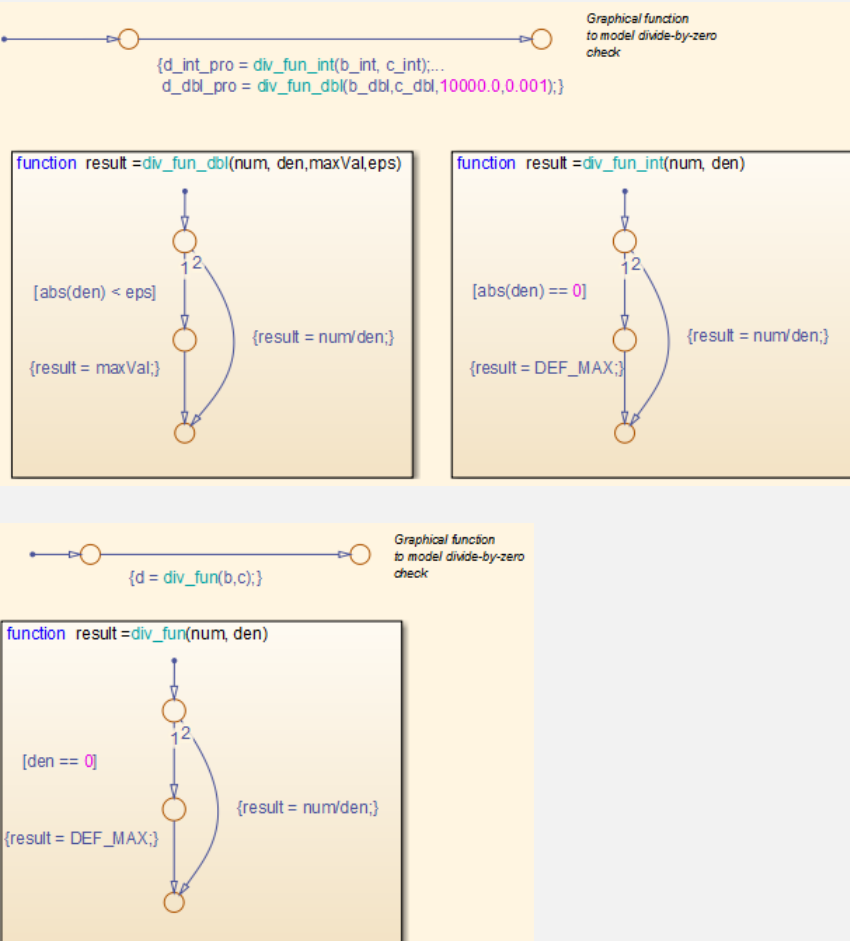
hisf_0211: Protect against use of unary operators in Stateflow Charts to improve code compliance

ID: Title	hisf_0211: Protect against use of unary operators in Stateflow Charts to improve code compliance
Description	To improve code compliance of the generated code:
	A Do not use unary minus operators on unsigned data types.
Note	The MATLAB and C action languages do not restrict the use of unary minus operators on unsigned expressions.
Rationale	Improve code compliance of the generated code.
Model Advisor Checks	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Stateflow > Check Stateflow charts for unary operators • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Stateflow > Check Stateflow charts for unary operators • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Stateflow > Check Stateflow charts for unary operators • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Stateflow > Check Stateflow charts for unary operators • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Stateflow > Check Stateflow charts for unary operators <p>For check details, see "Check Stateflow charts for unary operators" (Simulink Check).</p>

ID: Title	hisf_0211: Protect against use of unary operators in Stateflow Charts to improve code compliance
References	<ul style="list-style-type: none"> • DO-331 Section MB.6.3.1.b 'High-level requirements are accurate and consistent' • DO-331 Section MB.6.3.2.b 'Low-level requirements are accurate and consistent' • IEC 61508-3, Table A.3 (2) Strongly typed programming language • IEC 61508-3, Table A.4 (3) Defensive programming • IEC 62304, 5.5.3 - Software Unit acceptance criteria • ISO 26262-6, Table 1 (1b) Use of language subsets • ISO 26262-6, Table 1 (1c) Enforcement of strong typing • ISO 26262-6, Table 1 (1d) Use of defensive implementation techniques • EN 50128, Table A.4 (8) Strongly Typed Programming Language • EN 50128, Table A.3 (1) Defensive Programming • MISRA C:2012, Rule 10.1
Last Changed	R2017b

hisf_0213: Protect against divide-by-zero calculations in Stateflow charts to improve MISRA C:2012 compliance

ID: Title	hisf_0213: Protect against divide-by-zero calculations in Stateflow charts to improve MISRA C:2012 compliance	
Description	To improve MISRA C:2012 compliance of the generated code for floating point and integer-based operations, do one of the following:	
	A	Perform static analysis of the model to prove that division by zero is not possible
	B	Provide run-time error checking in the generated C code by explicitly modeling the error checking in Stateflow
	C	Modify the code generation process using Code Replacement Libraries (CRLs) to protect against division by zero
	D	For integer-based operations, clear configuration parameter Remove code that protects against division arithmetic exceptions
Note	<p>Using run-time error checking introduces additional computational and memory overhead in the generated code. Therefore, it is preferable to use static analysis tools to limit errors in the generated code.</p> <p>You can use the design error detection functionality in Simulink Design Verifier to perform the static analysis. For more information, see “Static Run-Time Error Detection” (Simulink Design Verifier). Alternatively, if you have a Simulink Design Verifier license, you can use Model Advisor check Detect Division by Zero to identify division-by-zero errors in your model.</p> <p>If static analysis determines that sections of the code can have a division by zero, then add run-time protection into that section of the model (see example). Using a modified CRL or selecting the parameter Remove code that protects against division arithmetic exceptions protects division operations against divide-by-zero operations. However, this action does introduce additional computational and memory overhead.</p> <p>Use only one of the run-time protections (B, C or D) in a model. Using more than one option can result in redundant protection operations.</p>	

ID: Title	hisf_0213: Protect against divide-by-zero calculations in Stateflow charts to improve MISRA C:2012 compliance	
Rationale	A,B, C,D	Improve MISRA C:2012 compliance of the generated code
References	<ul style="list-style-type: none"> MISRA C:2012, Dir 4.1 	
See Also	<ul style="list-style-type: none"> “What Is Code Replacement?” (Simulink Coder) and “Code Replacement Libraries” (Simulink Coder) “hisl_0002: Usage of Math Function blocks (rem and reciprocal)” on page 2-3 “hisl_0005: Usage of Product blocks” on page 2-10 “hisl_0054: Configuration Parameters > Code Generation > Optimization > Remove code that protects against division arithmetic exceptions” on page 5-30 Detect Division by Zero 	
Last Changed	R2018a	
Example	<p>Run-time divide by zero protection can be realized using a graphical function. Unique functions should be provided for each data type.</p>  <p>The example illustrates the implementation of run-time divide-by-zero protection using graphical functions. It shows two main examples:</p> <ul style="list-style-type: none"> Integer Division Protection: A graphical function block is shown with the code: <pre>{d_int_pro = div_fun_int(b_int, c_int);... d_dbl_pro = div_fun_dbl(b_dbl, c_dbl, 10000.0, 0.001);}</pre> Below this, two function blocks are detailed: <ul style="list-style-type: none"> div_fun_dbl: A function that takes <code>num</code>, <code>den</code>, <code>maxVal</code>, and <code>eps</code> as inputs. The Stateflow logic checks <code>[abs(den) < eps]</code>. If true, it sets <code>{result = maxVal;}</code>. If false, it sets <code>{result = num/den;}</code>. div_fun_int: A function that takes <code>num</code> and <code>den</code> as inputs. The Stateflow logic checks <code>[abs(den) == 0]</code>. If true, it sets <code>{result = DEF_MAX;}</code>. If false, it sets <code>{result = num/den;}</code>. General Division Protection: A graphical function block is shown with the code: <pre>{d = div_fun(b,c);}</pre> Below this, a function block is detailed: <ul style="list-style-type: none"> div_fun: A function that takes <code>num</code> and <code>den</code> as inputs. The Stateflow logic checks <code>[den == 0]</code>. If true, it sets <code>{result = DEF_MAX;}</code>. If false, it sets <code>{result = num/den;}</code>. 	

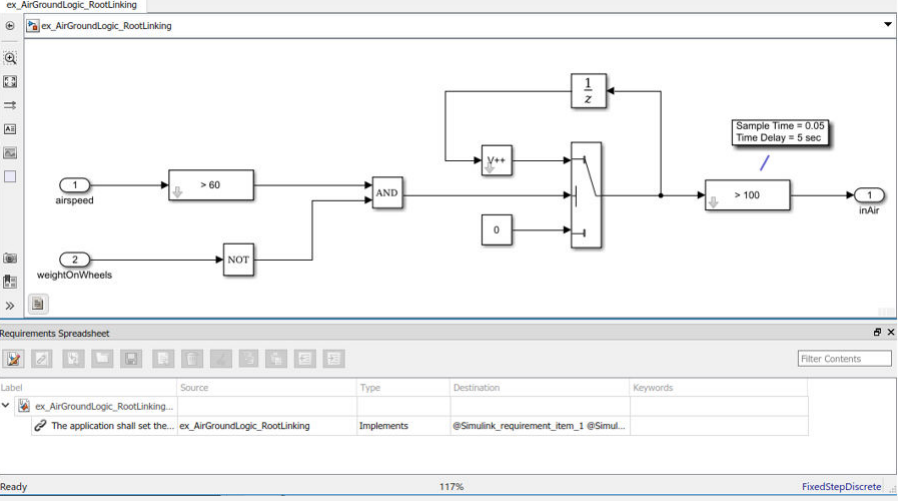
Requirements Considerations

Requirement Considerations

hisl_0070: Placement of requirement links in a model

ID: Title	hisl_0070: Placement of requirement links in a model							
Description	<p>Establish bidirectional traceability between model requirements and the model elements that are used to implement the requirement. A single element or combination of elements can link to requirements.</p> <p>When linking requirements, follow these guidelines.</p> <table border="1" data-bbox="402 615 1481 905"> <tr> <td data-bbox="402 615 495 720">A</td> <td data-bbox="500 615 1481 720">Apply requirement links to the lowest level component of model elements. Model elements that do not impact the model's behavior or the generated code are exempt from requirement linking. See Notes for additional information.</td> </tr> <tr> <td data-bbox="402 726 495 831">B</td> <td data-bbox="500 726 1481 831">At the project level, define the maximum number of unique requirement links associated with each component. A minimum of one requirement link is required.</td> </tr> <tr> <td data-bbox="402 837 495 905">C</td> <td data-bbox="500 837 1481 905">At the project level, define the maximum number of child model elements for each linked component.</td> </tr> </table>		A	Apply requirement links to the lowest level component of model elements. Model elements that do not impact the model's behavior or the generated code are exempt from requirement linking. See Notes for additional information.	B	At the project level, define the maximum number of unique requirement links associated with each component. A minimum of one requirement link is required.	C	At the project level, define the maximum number of child model elements for each linked component.
A	Apply requirement links to the lowest level component of model elements. Model elements that do not impact the model's behavior or the generated code are exempt from requirement linking. See Notes for additional information.							
B	At the project level, define the maximum number of unique requirement links associated with each component. A minimum of one requirement link is required.							
C	At the project level, define the maximum number of child model elements for each linked component.							
Notes	<p>Use Simulink Requirements™ to trace between the model and the requirements from which the model was developed. Apply user tags (Simulink Requirements) to define model elements as derived and/or safety requirements.</p> <p>To reduce the number of requirements that are linked to a model, apply requirements at the component-level. A component contains a group of model elements, for example:</p> <ul style="list-style-type: none"> • In Simulink, a component is a top-level block diagram, subsystem, MATLAB function, or area annotation. • In Stateflow, a component is a chart, superstate, box, Simulink function, or graphical function. <p>Components that contain <i>only</i> these model elements are exempt from requirement linking:</p> <ul style="list-style-type: none"> • Model Info, DocBlock, or System Requirements blocks • Area annotations • Model element with requirement links <p>When a linked component contains a nonexempt child model element, the child implements the associated requirement either in part or whole.</p>							
Rationale	A	Establishing requirement links at the component level captures the relationship of model elements. In addition, maintainability improves because the need to update requirement links for minor logic changes is reduced.						
	B, C	Support requirement change impact analysis.						

ID: Title	hisl_0070: Placement of requirement links in a model
Model Advisor Check	<ul style="list-style-type: none"> • By Task > Modeling Standards for DO-178C/DO-331 > High-Integrity Systems > Requirements > Check for model elements that do not link to requirements • By Task > Modeling Standards for IEC 61508 > High-Integrity Systems > Requirements > Check for model elements that do not link to requirements • By Task > Modeling Standards for IEC 62304 > High-Integrity Systems > Requirements > Check for model elements that do not link to requirements • By Task > Modeling Standards for ISO 26262 > High-Integrity Systems > Requirements > Check for model elements that do not link to requirements • By Task > Modeling Standards for EN 50128 > High-Integrity Systems > Requirements > Check for model elements that do not link to requirements <p>For check details, see “Check for model elements that do not link to requirements” (Simulink Check).</p>
References	<ul style="list-style-type: none"> • DO-331, Section MB.6.3.1.f - 'High-level requirements trace to system requirements' • DO-331, Section MB.6.3.2.f - 'Low-level requirements trace to high-level requirements' • IEC 61508-3, Table A.2 (12) - 'Computer-aided specification and design tools' • IEC 61508-3, Table A.2 (9) - 'Forward traceability between the software safety requirements specification and software architecture' • IEC 61508-3, Table A.2 (10) - 'Backward traceability between the software safety requirements specification and software architecture' • IEC 61508-3, Table A.4 (8) - 'Forward traceability between the software safety requirements specification and software design' • IEC 61508-3, Table A.8 (1) - 'Impact analysis' • IEC 62304, 5.2 - 'Software requirements analysis' • IEC 62304, 7.4.2 - 'Analyze impact of software changes on existing risk control measures' • ISO 26262-6, Table 2 (1a) - 'Natural language' • ISO 26262-6, Table 3 (1b) - 'Restricted size and complexity of software components' • ISO 26262-6: 7.4.2.a - The verifiability of the software architectural design • ISO 26262-8: 8.4.3 Change request analysis • EN 50128, Table A.3 (23) - 'Modeling supported by computer aided design and specification tools' • EN 50128, Table D.58 - Traceability • EN 50128, Table A.10 (1) - 'Impact Analysis'
See Also	“Requirements Traceability” (Simulink Requirements)
Last Changed	R2017b

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<p>Examples</p>	<p>Recommended: Requirement links on parent component</p> <p>Requirement link placed at the top level model with no subsystems.</p> 
	<p>Recommended: Requirement links placed on area annotation</p> <p>Requirement link placed on an area annotation.</p> 